Roundabouts: Part 3
Course# TE4033

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6.1 Introduction

Designing the geometry of a roundabout involves choosing between trade-offs of safety and capacity. Roundabouts operate most safely when their geometry forces traffic to enter and circulate at slow speeds. Horizontal curvature and narrow pavement widths are used to produce this reduced-speed environment. Conversely, the capacity of roundabouts is negatively affected by these low-speed design elements. As the widths and radii of entry and circulatory roadways are reduced, so also the capacity of the roundabout is reduced. Furthermore, many of the geometric parameters are governed by the maneuvering requirements of the largest vehicles expected to travel through the intersection. Thus, designing a roundabout is a process of determining the optimal balance between safety provisions, operational performance, and large vehicle accommodation.

While the basic form and features of roundabouts are uniform regardless of their location, many of the design techniques and parameters are different, depending on the speed environment and desired capacity at individual sites. In rural environments where approach speeds are high and bicycle and pedestrian use may be minimal, the design objectives are significantly different from roundabouts in urban environments where bicycle and pedestrian safety are a primary concern. Additionally, many of the design techniques are substantially different for single-lane roundabouts than for roundabouts with multiple entry lanes.

This chapter is organized so that the fundamental design principles common among all roundabout types are presented first. More detailed design considerations specific to multilane roundabouts, rural roundabouts, and mini-roundabouts are given in subsequent sections of the chapter.

6.1.1 Geometric elements

Exhibit 6-1 provides a review of the basic geometric features and dimensions of a roundabout. Chapter 1 provided the definitions of these elements.

6.1.2 Design process

The process of designing roundabouts, more so than other forms of intersections, requires a considerable amount of iteration among geometric layout, operational analysis, and safety evaluation. As described in Chapters 4 and 5, minor adjustments in geometry can result in significant changes in the safety and/or operational performance. Thus, the designer often needs to revise and refine the initial layout attempt to enhance its capacity and safety. It is rare to produce an optimal geometric design on the first attempt. Exhibit 6-2 provides a graphical flowchart for the process of designing and evaluating a roundabout.
Exhibit 6-1. Basic geometric elements of a roundabout.

Exhibit 6-2. Roundabout design process.
Because roundabout design is such an iterative process, in which small changes in geometry can result in substantial changes to operational and safety performance, it may be advisable to prepare the initial layout drawings at a sketch level of detail. Although it is easy to get caught into the desire to design each of the individual components of the geometry such that it complies with the specifications provided in this chapter, it is much more important that the individual components are compatible with each other so that the roundabout will meet its overall performance objectives. Before the details of the geometry are defined, three fundamental elements must be determined in the preliminary design stage:

1. The optimal roundabout size;
2. The optimal position; and
3. The optimal alignment and arrangement of approach legs.

### 6.2 General Design Principles

This section describes the fundamental design principles common among all categories of roundabouts. Guidelines for the design of each geometric element are provided in the following section. Further guidelines specific to double-lane roundabouts, rural roundabouts, and mini-roundabouts are given in subsequent sections. Note that double-lane roundabout design is significantly different from single-lane roundabout design, and many of the techniques used in single-lane roundabout design do not directly transfer to double-lane design.

#### 6.2.1 Speeds through the roundabout

Because it has profound impacts on safety, achieving appropriate vehicular speeds through the roundabout is the most critical design objective. A well-designed roundabout reduces the relative speeds between conflicting traffic streams by requiring vehicles to negotiate the roundabout along a curved path.

**6.2.1.1 Speed profiles**

Exhibit 6-3 shows the operating speeds of typical vehicles approaching and negotiating a roundabout. Approach speeds of 40, 55, and 70 km/h (25, 35, and 45 mph, respectively) about 100 m (325 ft) from the center of the roundabout are shown. Deceleration begins before this time, with circulating drivers operating at approximately the same speed on the roundabout. The relatively uniform negotiation speed of all drivers on the roundabout means that drivers are able to more easily choose their desired paths in a safe and efficient manner.

**6.2.1.2 Design speed**

International studies have shown that increasing the vehicle path curvature decreases the relative speed between entering and circulating vehicles and thus usually results in decreases in the entering-circulating and exiting-circulating vehicle crash rates. However, at multilane roundabouts, increasing vehicle path curvature creates greater side friction between adjacent traffic streams and can result in more vehicles cutting across lanes and higher potential for sideswipe crashes (2). Thus, for each roundabout, there exists an optimum design speed to minimize crashes.
Recommended maximum entry design speeds for roundabouts at various intersection site categories are provided in Exhibit 6-4.

<table>
<thead>
<tr>
<th>Site Category</th>
<th>Recommended Maximum Entry Design Speed</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mini-Roundabout</td>
<td>25 km/h (15 mph)</td>
</tr>
<tr>
<td>Urban Compact</td>
<td>25 km/h (15 mph)</td>
</tr>
<tr>
<td>Urban Single Lane</td>
<td>35 km/h (20 mph)</td>
</tr>
<tr>
<td>Urban Double Lane</td>
<td>40 km/h (25 mph)</td>
</tr>
<tr>
<td>Rural Single Lane</td>
<td>40 km/h (25 mph)</td>
</tr>
<tr>
<td>Rural Double Lane</td>
<td>50 km/h (30 mph)</td>
</tr>
</tbody>
</table>

Exhibit 6-3. Sample theoretical speed profile (urban compact roundabout).

Exhibit 6-4. Recommended maximum entry design speeds.
6.2.1.3 Vehicle paths

To determine the speed of a roundabout, the fastest path allowed by the geometry is drawn. This is the smoothest, flattest path possible for a single vehicle, in the absence of other traffic and ignoring all lane markings, traversing through the entry, around the central island, and out the exit. Usually the fastest possible path is the through movement, but in some cases it may be a right turn movement.

A vehicle is assumed to be 2 m (6 ft) wide and to maintain a minimum clearance of 0.5 m (2 ft) from a roadway centerline or concrete curb and flush with a painted edge line (2). Thus the centerline of the vehicle path is drawn with the following distances to the particular geometric features:

- 1.5 m (5 ft) from a concrete curb,
- 1.5 m (5 ft) from a roadway centerline, and
- 1.0 m (3 ft) from a painted edge line.

Exhibits 6-5 and 6-6 illustrate the construction of the fastest vehicle paths at a single-lane roundabout and at a double-lane roundabout, respectively. Exhibit 6-7 provides an example of an approach at which the right-turn path is more critical than the through movement.
Exhibit 6-6. Fastest vehicle path through double-lane roundabout.

Exhibit 6-7. Example of critical right-turn movement.
The entry path radius should not be significantly larger than the circulatory radius.

Draw the fastest path for all roundabout approaches.

As shown in Exhibits 6-5 and 6-6, the fastest path for the through movement is a series of reverse curves (i.e., a curve to the right, followed by a curve to the left, followed by a curve to the right). When drawing the path, a short length of tangent should be drawn between consecutive curves to account for the time it takes for a driver to turn the steering wheel. It may be initially better to draw the path free-hand, rather than using drafting templates or a computer-aided design (CAD) program. The freehand technique may provide a more natural representation of the way a driver negotiates the roundabout, with smooth transitions connecting curves and tangents. Having sketched the fastest path, the designer can then measure the minimum radii using suitable curve templates or by replicating the path in CAD and using it to determine the radii.

The design speed of the roundabout is determined from the smallest radius along the fastest allowable path. The smallest radius usually occurs on the circulatory roadway as the vehicle curves to the left around the central island. However, it is important when designing the roundabout geometry that the radius of the entry path (i.e., as the vehicle curves to the right through entry geometry) not be significantly larger than the circulatory path radius.

The fastest path should be drawn for all approaches of the roundabout. Because the construction of the fastest path is a subjective process requiring a certain amount of personal judgment, it may be advisable to obtain a second opinion.

6.2.1.4 Speed-curve relationship

The relationship between travel speed and horizontal curvature is documented in the American Association of State Highway and Transportation Officials’ document, A Policy on Geometric Design of Highways and Streets, commonly known as the Green Book (4). Equation 6-1 can be used to calculate the design speed for a given travel path radius.

\[
V = \sqrt{127R(e+f)} \quad (6-1a, \text{metric})
\]

\[
V = \sqrt{15R(e+f)} \quad (6-1b, \text{U.S. customary})
\]

where: \( V \) = Design speed, \( R \) = Radius, \( e \) = superelevation, \( f \) = side friction factor

\( \text{km/h} \) \( \text{m} \) \( \text{m/m} \) \( \text{ft/ft} \)

Superelevation values are usually assumed to be +0.02 for entry and exit curves and -0.02 for curves around the central island. For more details related to superelevation design, see Section 6.3.11.

Values for side friction factor can be determined in accordance with the AASHTO relation for curves at intersections (see 1994 AASHTO Figure III-19 (4)). The coefficient of friction between a vehicle’s tires and the pavement varies with the vehicle’s speed, as shown in Exhibits 6-8 and 6-9 for metric and U.S. customary units, respectively.
Exhibit 6-8. Side friction factors at various speeds (metric units).

Exhibit 6-9. Side friction factors at various speeds (U.S. customary units).
Using the appropriate friction factors corresponding to each speed, Exhibits 6-10
and 6-11 present charts in metric and U.S. customary units, respectively, showing
the speed-radius relationship for curves for both a +0.02 superelevation and -0.02
superelevation.

**Exhibit 6-10.** Speed-radius relationship (metric units).

**Exhibit 6-11.** Speed-radius relationship (U.S. customary units.)
6.2.15 Speed consistency

In addition to achieving an appropriate design speed for the fastest movements, another important objective is to achieve consistent speeds for all movements. Along with overall reductions in speed, speed consistency can help to minimize the crash rate and severity between conflicting streams of vehicles. It also simplifies the task of merging into the conflicting traffic stream, minimizing critical gaps, thus optimizing entry capacity. This principle has two implications:

1. The relative speeds between consecutive geometric elements should be minimized; and
2. The relative speeds between conflicting traffic streams should be minimized.

As shown in Exhibit 6-12, five critical path radii must be checked for each approach. \( R_1 \), the entry path radius, is the minimum radius on the fastest through path prior to the yield line. \( R_2 \), the circulating path radius, is the minimum radius on the fastest through path around the central island. \( R_3 \), the exit path radius, is the minimum radius on the fastest through path into the exit. \( R_4 \), the left-turn path radius, is the minimum radius on the path of the conflicting left-turn movement. \( R_5 \), the right-turn path radius, is the minimum radius on the fastest path of a right-turning vehicle. It is important to note that these vehicular path radii are not the same as the curb radii. First the basic curb geometry is laid out, and then the vehicle paths are drawn in accordance with the procedures described in Section 6.2.1.3.
On the fastest path, it is desirable for $R_1$ to be smaller than $R_2$, which in turn should be smaller than $R_3$. This ensures that speeds will be reduced to their lowest level at the roundabout entry and will thereby reduce the likelihood of loss-of-control crashes. It also helps to reduce the speed differential between entering and circulating traffic, thereby reducing the entering-circulating vehicle crash rate. However, in some cases it may not be possible to achieve an $R_1$ value less than $R_2$ within given right-of-way or topographic constraints. In such cases, it is acceptable for $R_1$ to be greater than $R_2$, provided the relative difference in speeds is less than 20 km/h (12 mph) and preferably less than 10 km/h (6 mph).

At single-lane roundabouts, it is relatively simple to reduce the value of $R_1$. The curb radius at the entry can be reduced or the alignment of the approach can be shifted further to the left to achieve a slower entry speed (with the potential for higher exit speeds that may put pedestrians at risk). However, at double-lane roundabouts, it is generally more difficult as overly small entry curves can cause the natural path of adjacent traffic streams to overlap. Path overlap happens when the geometry leads a vehicle in the left approach lane to naturally sweep across the right approach lane just before the approach line to avoid the central island. It may also happen within the circulatory roadway when a vehicle entering from the right-hand lane naturally cuts across the left side of the circulatory roadway close to the central island. When path overlap occurs at double-lane roundabouts, it may reduce capacity and increase crash risk. Therefore, care must be taken when designing double-lane roundabouts to achieve ideal values for $R_1$, $R_2$, and $R_3$. Section 6.4 provides further guidance on eliminating path overlap at double-lane roundabouts.

The exit radius, $R_3$, should not be less than $R_1$ or $R_2$ in order to minimize loss-of-control crashes. At single-lane roundabouts with pedestrian activity, exit radii may still be small (the same or slightly larger than $R_2$) in order to minimize exit speeds. However, at double-lane roundabouts, additional care must be taken to minimize the likelihood of exiting path overlap. Exit path overlap can occur at the exit when a vehicle on the left side of the circulatory roadway (next to the central island) exits into the right-hand exit lane. Where no pedestrians are expected, the exit radii should be just large enough to minimize the likelihood of exiting path overlap. Where pedestrians are present, tighter exit curvature may be necessary to ensure sufficiently low speeds at the downstream pedestrian crossing.

The radius of the conflicting left-turn movement, $R_4$, must be evaluated in order to ensure that the maximum speed differential between entering and circulating traffic is no more than 20 km/h (12 mph). The left-turn movement is the critical traffic stream because it has the lowest circulating speed. Large differentials between entry and circulating speeds may result in an increase in single-vehicle crashes due to loss of control. Generally, $R_4$ can be determined by adding 1.5 m (5 ft) to the central island radius. Based on this assumption, Exhibits 6-13 and 6-14 show approximate $R_4$ values and corresponding maximum $R_1$ values for various inscribed circle diameters in metric and U.S. customary units, respectively.

The natural path of a vehicle is the path that a driver would take in the absence of other conflicting vehicles.
Finally, the radius of the fastest possible right-turn path, $R_5$, is evaluated. Like $R_1$, the right-turn radius should have a design speed at or below the maximum design speed of the roundabout and no more than 20 km/h (12 mph) above the conflicting $R_4$ design speed.

<table>
<thead>
<tr>
<th>Inscribed Circle Diameter (m)</th>
<th>Approximate $R_4$ Value</th>
<th>Maximum $R_1$ Value</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Radius (m)</td>
<td>Speed (km/h)</td>
</tr>
<tr>
<td>Single-Lane Roundabout</td>
<td></td>
<td></td>
</tr>
<tr>
<td>30</td>
<td>11</td>
<td>21</td>
</tr>
<tr>
<td>35</td>
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<td>25</td>
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<td>45</td>
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<tr>
<td>Double-Lane Roundabout</td>
<td></td>
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<tr>
<td>45</td>
<td>15</td>
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<td>70</td>
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<table>
<thead>
<tr>
<th>Inscribed Circle Diameter (m)</th>
<th>Approximate $R_4$ Value</th>
<th>Maximum $R_1$ Value</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Radius (ft)</td>
<td>Speed (mph)</td>
</tr>
<tr>
<td>Single-Lane Roundabout</td>
<td></td>
<td></td>
</tr>
<tr>
<td>100</td>
<td>35</td>
<td>13</td>
</tr>
<tr>
<td>115</td>
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<td>130</td>
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<tr>
<td>150</td>
<td>65</td>
<td>15</td>
</tr>
<tr>
<td>Double-Lane Roundabout</td>
<td></td>
<td></td>
</tr>
<tr>
<td>150</td>
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<td>15</td>
</tr>
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<td>165</td>
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<td>215</td>
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<td>18</td>
</tr>
<tr>
<td>230</td>
<td>90</td>
<td>18</td>
</tr>
</tbody>
</table>
6.2.2 Design vehicle

Another important factor determining a roundabout’s layout is the need to accommodate the largest motorized vehicle likely to use the intersection. The turning path requirements of this vehicle, termed hereafter the design vehicle, will dictate many of the roundabout’s dimensions. Before beginning the design process, the designer must be conscious of the design vehicle and possess the appropriate vehicle turning templates or a CAD-based vehicle turning path program to determine the vehicle’s swept path.

The choice of design vehicle will vary depending upon the approaching roadway types and the surrounding land use characteristics. The local or State agency with jurisdiction of the associated roadways should usually be consulted to identify the design vehicle at each site. The AASHTO A Policy on Geometric Design of Highways and Streets provides the dimensions and turning path requirements for a variety of common highway vehicles (4). Commonly, WB-15 (WB-50) vehicles are the largest vehicles along collectors and arterials. Larger trucks, such as WB-20 (WB-67) vehicles, may need to be addressed at intersections on interstate freeways or State highway systems. Smaller design vehicles may often be chosen for local street intersections.

In general, larger roundabouts need to be used to accommodate large vehicles while maintaining low speeds for passenger vehicles. However, in some cases, land constraints may limit the ability to accommodate large semi-trailer combinations while achieving adequate deflection for small vehicles. At such times, a truck apron may be used to provide additional traversable area around the central island for large semi-trailers. Truck aprons, though, provide a lower level of operation than standard nonmountable islands and should be used only when there is no other means of providing adequate deflection while accommodating the design vehicle.

Exhibits 6-15 and 6-16 demonstrate the use of a CAD-based computer program to determine the vehicle’s swept path through the critical turning movements.

Exhibit 6-16. Left-turn and right-turn swept paths of WB-15 (WB-50) vehicle.
6.2.3 Nonmotorized design users

Like the motorized design vehicle, the design criteria of nonmotorized potential roundabout users (bicyclists, pedestrians, skaters, wheelchair users, strollers, etc.) should be considered when developing many of the geometric elements of a roundabout design. These users span a wide range of ages and abilities that can have a significant effect on the design of a facility.

The basic design dimensions for various design users are given in Exhibit 6-17 (5).

<table>
<thead>
<tr>
<th>User</th>
<th>Dimension Affected Roundabout Features</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Bicycles</strong></td>
<td></td>
</tr>
<tr>
<td>Length</td>
<td>1.8 m (5.9 ft)</td>
</tr>
<tr>
<td>Minimum operating width</td>
<td>1.5 m (4.9 ft)</td>
</tr>
<tr>
<td>Lateral clearance on each side</td>
<td>0.6 m (2.0 ft); 1.0 m (3.3 ft)</td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Pedestrian (walking)</strong></td>
<td></td>
</tr>
<tr>
<td>Width</td>
<td>0.5 m (1.6 ft)</td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Wheelchair</strong></td>
<td></td>
</tr>
<tr>
<td>Minimum width</td>
<td>0.75 m (2.5 ft)</td>
</tr>
<tr>
<td>Operating width</td>
<td>0.90 m (3.0 ft)</td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Person pushing stroller</strong></td>
<td></td>
</tr>
<tr>
<td>Length</td>
<td>1.70 m (5.6 ft)</td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Skaters</strong></td>
<td></td>
</tr>
<tr>
<td>Typical operating width</td>
<td>1.8 m (6 ft)</td>
</tr>
</tbody>
</table>

Source: (5)

6.2.4 Alignment of approaches and entries

In general, the roundabout is optimally located when the centerlines of all approach legs pass through the center of the inscribed circle. This location usually allows the geometry to be adequately designed so that vehicles will maintain slow speeds through both the entries and the exits. The radial alignment also makes the central island more conspicuous to approaching drivers.

If it is not possible to align the legs through the center point, a slight offset to the left (i.e., the centerline passes to the left of the roundabout’s center point) is acceptable. This alignment will still allow sufficient curvature to be achieved at the entry, which is of supreme importance. In some cases (particularly when the inscribed circle is relatively small), it may be beneficial to introduce a slight offset of the approaches to the left in order to enhance the entry curvature. However, care must be taken to ensure that such an approach offset does not produce an excessively tangential exit. Especially in urban environments, it is important that the exit...
geometry produce a sufficiently curved exit path in order to keep vehicle speeds low and reduce the risk for pedestrians.

It is almost never acceptable for an approach alignment to be offset to the right of the roundabout’s center point. This alignment brings the approach in at a more tangential angle and reduces the opportunity to provide sufficient entry curvature. Vehicles will be able to enter the roundabout too fast, resulting in more loss-of-control crashes and higher crash rates between entering and circulating vehicles. Exhibit 6-18 illustrates the preferred radial alignment of entries.

In addition, it is desirable to equally space the angles between entries. This provides optimal separation between successive entries and exits. This results in optimal angles of 90 degrees for four-leg roundabouts, 72 degrees for five-leg roundabouts, and so on. This is consistent with findings of the British accident prediction models described in Chapter 5.

Exhibit 6-18. Radial alignment of entries.

6.3 Geometric Elements

This section presents specific parameters and guidelines for the design of each geometric element of a roundabout. The designer must keep in mind, however, that these components are not independent of each other. The interaction between the components of the geometry is far more important than the individual pieces. Care must be taken to ensure that the geometric elements are all compatible with each other so that the overall safety and capacity objectives are met.

6.3.1 Inscribed circle diameter

The inscribed circle diameter is the distance across the circle inscribed by the outer curb (or edge) of the circulatory roadway. As illustrated in Exhibit 6-1, it is the sum of the central island diameter (which includes the apron, if present) and twice the circulatory roadway. The inscribed circle diameter is determined by a number of design objectives. The designer often has to experiment with varying diameters before determining the optimal size at a given location.
At single-lane roundabouts, the size of the inscribed circle is largely dependent upon the turning requirements of the design vehicle. The diameter must be large enough to accommodate the design vehicle while maintaining adequate deflection curvature to ensure safe travel speeds for smaller vehicles. However, the circulatory roadway width, entry and exit widths, entry and exit radii, and entry and exit angles also play a significant role in accommodating the design vehicle and providing deflection. Careful selection of these geometric elements may allow a smaller inscribed circle diameter to be used in constrained locations. In general, the inscribed circle diameter should be a minimum of 30 m (100 ft) to accommodate a WB-15 (WB-50) design vehicle. Smaller roundabouts can be used for some local street or collector street intersections, where the design vehicle may be a bus or single-unit truck.

At double-lane roundabouts, accommodating the design vehicle is usually not a constraint. The size of the roundabout is usually determined either by the need to achieve deflection or by the need to fit the entries and exits around the circumference with reasonable entry and exit radii between them. Generally, the inscribed circle diameter of a double-lane roundabout should be a minimum of 45 m (150 ft).

In general, smaller inscribed diameters are better for overall safety because they help to maintain lower speeds. In high-speed environments, however, the design of the approach geometry is more critical than in low-speed environments. Larger inscribed diameters generally allow for the provision of better approach geometry, which leads to a decrease in vehicle approach speeds. Larger inscribed diameters also reduce the angle formed between entering and circulating vehicle paths, thereby reducing the relative speed between these vehicles and leading to reduced entering-circulating crash rates (2). Therefore, roundabouts in high-speed environments may require diameters that are somewhat larger than those recommended for low-speed environments. Very large diameters (greater than 60 m [200 ft]), however, should generally not be used because they will have high circulating speeds and more crashes with greater severity. Exhibit 6-19 provides recommended ranges of inscribed circle diameters for various site locations.

**Exhibit 6-19.** Recommended inscribed circle diameter ranges.

<table>
<thead>
<tr>
<th>Site Category</th>
<th>Typical Design Vehicle</th>
<th>Inscribed Circle Diameter Range*</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mini-Roundabout</td>
<td>Single-Unit Truck</td>
<td>13–25m (45–80 ft)</td>
</tr>
<tr>
<td>Urban Compact</td>
<td>Single-Unit Truck/Bus</td>
<td>25–30m (80–100 ft)</td>
</tr>
<tr>
<td>Urban Single Lane</td>
<td>WB-15 (WB-50)</td>
<td>30–40m (100–130 ft)</td>
</tr>
<tr>
<td>Urban Double Lane</td>
<td>WB-15 (WB-50)</td>
<td>45–55m (150–180 ft)</td>
</tr>
<tr>
<td>Rural Single Lane</td>
<td>WB-20 (WB-67)</td>
<td>35–40m (115–130 ft)</td>
</tr>
<tr>
<td>Rural Double Lane</td>
<td>WB-20 (WB-67)</td>
<td>55–60m (180–200 ft)</td>
</tr>
</tbody>
</table>

* Assumes 90-degree angles between entries and no more than four legs.
6.3.2 Entry width

Entry width is the largest determinant of a roundabout's capacity. The capacity of an approach is not dependent merely on the number of entering lanes, but on the total width of the entry. In other words, the entry capacity increases steadily with incremental increases to the entry width. Therefore, the basic sizes of entries and circulatory roadways are generally described in terms of width, not number of lanes. Entries that are of sufficient width to accommodate multiple traffic streams (at least 6.0 m [20 ft]) are striped to designate separate lanes. However, the circulatory roadway is usually not striped, even when more than one lane of traffic is expected to circulate (for more details related to roadway markings, see Chapter 7).

As shown in Exhibit 6-1, entry width is measured from the point where the yield line intersects the left edge of the traveled-way to the right edge of the traveled-way, along a line perpendicular to the right curb line. The width of each entry is dictated by the needs of the entering traffic stream. It is based on design traffic volumes and can be determined in terms of the number of entry lanes by using Chapter 4 of this guide. The circulatory roadway must be at least as wide as the widest entry and must maintain a constant width throughout.

To maximize the roundabout’s safety, entry widths should be kept to a minimum. The capacity requirements and performance objectives will dictate that each entry be a certain width, with a number of entry lanes. In addition, the turning requirements of the design vehicle may require that the entry be wider still. However, larger entry and circulatory widths increase crash frequency. Therefore, determining the entry width and circulatory roadway width involves a trade-off between capacity and safety. The design should provide the minimum width necessary for capacity and accommodation of the design vehicle in order to maintain the highest level of safety. Typical entry widths for single-lane entrances range from 4.3 to 4.9 m (14 to 16 ft); however, values higher or lower than this range may be required for site-specific design vehicle and speed requirements for critical vehicle paths.

When the capacity requirements can only be met by increasing the entry width, this can be done in two ways:

1. By adding a full lane upstream of the roundabout and maintaining parallel lanes through the entry geometry; or

2. By widening the approach gradually (flaring) through the entry geometry.

Exhibit 6-20 and Exhibit 6-21 illustrate these two widening options.
As discussed in Chapter 4, flaring is an effective means of increasing capacity without requiring as much right-of-way as a full lane addition. While increasing the length of flare increases capacity, it does not increase crash frequency. Consequently, the crash frequency for two approaches with the same entry width will be essentially the same, whether they have parallel entry lanes or flared entry designs. Entry widths should therefore be minimized and flare lengths maximized to achieve the desired capacity with minimal effect on crashes. Generally, flare lengths should be a minimum of 25 m (80 ft) in urban areas and 40 m (130 ft) in rural areas. However, if right-of-way is constrained, shorter lengths can be used with noticeable effects on capacity (see Chapter 4).
In some cases, a roundabout designed to accommodate design year traffic volumes, typically projected 20 years from the present, can result in substantially wider entries and circulatory roadway than needed in the earlier years of operation. Because safety will be significantly reduced by the increase in entry width, the designer may wish to consider a two-phase design solution. In this case, the first-phase design would provide the entry width requirements for near-term traffic volumes with the ability to easily expand the entries and circulatory roadway to accommodate future traffic volumes. The interim solution should be accomplished by first laying out the ultimate plan, then designing the first phase within the ultimate curb lines. The interim roundabout is often constructed with the ultimate inscribed circle diameter, but with a larger central island and splitter islands. At the time additional capacity is needed, the splitter and central islands can be reduced in size to provide additional widths at the entries, exits, and circulatory roadway.

6.3.3 Circulatory roadway width

The required width of the circulatory roadway is determined from the width of the entries and the turning requirements of the design vehicle. In general, it should always be at least as wide as the maximum entry width (up to 120 percent of the maximum entry width) and should remain constant throughout the roundabout (3).

6.3.3.1 Single-lane roundabouts

At single-lane roundabouts, the circulatory roadway should just accommodate the design vehicle. Appropriate vehicle-turning templates or a CAD-based computer program should be used to determine the swept path of the design vehicle through each of the turning movements. Usually the left-turn movement is the critical path for determining circulatory roadway width. In accordance with AASHTO policy, a minimum clearance of 0.6 m (2 ft) should be provided between the outside edge of the vehicle’s tire track and the curb line. AASHTO Table III-19 (1994 edition) provides derived widths required for various radii for each standard design vehicle.

In some cases (particularly where the inscribed diameter is small or the design vehicle is large) the turning requirements of the design vehicle may dictate that the circulatory roadway be so wide that the amount of deflection necessary to slow passenger vehicles is compromised. In such cases, the circulatory roadway width can be reduced and a truck apron, placed behind a mountable curb on the central island, can be used to accommodate larger vehicles. However, truck aprons generally provide a lower level of operation than standard nonmountable islands. They are sometimes driven over by four-wheel drive automobiles, may surprise inattentive motorcyclists, and can cause load shifting on trucks. They should, therefore, be used only when there is no other means of providing adequate deflection while accommodating the design vehicle.

6.3.3.2 Double-lane roundabouts

At double-lane roundabouts, the circulatory roadway width is usually not governed by the design vehicle. The width required for one, two, or three vehicles, depending on the number of lanes at the widest entry, to travel simultaneously through the roundabout should be used to establish the circulatory roadway width. The
combination of vehicle types to be accommodated side-by-side is dependent upon the specific traffic conditions at each site. If the entering traffic is predominantly passenger cars and single-unit trucks (AASHTO P and SU vehicles), where semi-trailer traffic is infrequent, it may be appropriate to design the width for two passenger vehicles or a passenger car and a single-unit truck side-by-side. If semi-trailer traffic is relatively frequent (greater than 10 percent), it may be necessary to provide sufficient width for the simultaneous passage of a semi-trailer in combination with a P or SU vehicle.

Exhibit 6-22 provides minimum recommended circulatory roadway widths for two-lane roundabouts where semi-trailer traffic is relatively infrequent.

<table>
<thead>
<tr>
<th>Inscribed Circle Diameter</th>
<th>Minimum Circulatory Lane Width*</th>
<th>Central Island Diameter</th>
</tr>
</thead>
<tbody>
<tr>
<td>45 m (150 ft)</td>
<td>9.8 m (32 ft)</td>
<td>25.4 m (86 ft)</td>
</tr>
<tr>
<td>50 m (165 ft)</td>
<td>9.3 m (31 ft)</td>
<td>31.4 m (103 ft)</td>
</tr>
<tr>
<td>55 m (180 ft)</td>
<td>9.1 m (30 ft)</td>
<td>36.8 m (120 ft)</td>
</tr>
<tr>
<td>60 m (200 ft)</td>
<td>9.1 m (30 ft)</td>
<td>41.8 m (140 ft)</td>
</tr>
<tr>
<td>65 m (215 ft)</td>
<td>8.7 m (29 ft)</td>
<td>47.6 m (157 ft)</td>
</tr>
<tr>
<td>70 m (230 ft)</td>
<td>8.7 m (29 ft)</td>
<td>52.6 m (172 ft)</td>
</tr>
</tbody>
</table>

* Based on 1994 AASHTO Table III-20, Case III(A) (4). Assumes infrequent semi-trailer use (typically less than 5 percent of the total traffic). Refer to AASHTO for cases with higher truck percentages.

### 6.3.4 Central island

The central island of a roundabout is the raised, nontraversable area encompassed by the circulatory roadway; this area may also include a traversable apron. The island is typically landscaped for aesthetic reasons and to enhance driver recognition of the roundabout upon approach. Central islands should always be raised, not depressed, as depressed islands are difficult for approaching drivers to recognize.

In general, the central island should be circular in shape. A circular-shaped central island with a constant-radius circulatory roadway helps promote constant speeds around the central island. Oval or irregular shapes, on the other hand, are more difficult to drive and can promote higher speeds on the straight sections and reduced speeds on the arcs of the oval. This speed differential may make it harder for entering vehicles to judge the speed and acceptability of gaps in the circulatory traffic stream. It can also be deceptive to circulating drivers, leading to more loss-of-control crashes. Noncircular central islands have the above disadvantages to a rapidly increasing degree as they get larger because circulating speeds are higher. Oval shapes are generally not such a problem if they are relatively small and speeds are low. Raindrop-shaped islands may be used in areas where certain movements do not exist, such as interchanges (see Chapter 8), or at locations where certain turning movements cannot be safely accommodated, such as roundabouts with one approach on a relatively steep grade.
As described in Section 6.2.1, the size of the central island plays a key role in determining the amount of deflection imposed on the through vehicle’s path. However, its diameter is entirely dependent upon the inscribed circle diameter and the required circulatory roadway width (see Sections 6.3.1 and 6.3.3, respectively). Therefore, once the inscribed diameter, circulatory roadway width, and initial entry geometry have been established, the fastest vehicle path must be drawn though the layout, as described in Section 6.2.1.3, to determine if the central island size is adequate. If the fastest path exceeds the design speed, the central island size may need to be increased, thus increasing the overall inscribed circle diameter. There may be other methods for increasing deflection without increasing the inscribed diameter, such as offsetting the approach alignment to the left, reducing the entry width, or reducing the entry radius. These treatments, however, may preclude the ability to accommodate the design vehicle.

In cases where right-of-way, topography, or other constraints preclude the ability to expand the inscribed circle diameter, a mountable apron may be added to the outer edge of the central island. This provides additional paved area to allow the over-tracking of large semi-trailer vehicles on the central island without compromising the deflection for smaller vehicles. Exhibit 6-23 shows a typical central island with a traversable apron.

Where aprons are used, they should be designed so that they are traversable by trucks, but discourage passenger vehicles from using them. They should generally be 1 to 4 m (3 to 13 ft) wide and have a cross slope of 3 to 4 percent away from the central island. To discourage use by passenger vehicles, the outer edge of the apron should be raised a minimum of 30 mm (1.2 in) above the circulatory roadway surface (6). The apron should be constructed of colored and/or textured paving.
materials to differentiate it from the circulatory roadway. Care must be taken to ensure that delivery trucks will not experience load shifting as their rear trailer wheels track across the apron.

Issues regarding landscaping and other treatments within the central island are discussed in Chapter 7.

In general, roundabouts in rural environments typically need larger central islands than urban roundabouts in order to enhance their visibility and to enable the design of better approach geometry (2).

### 6.3.5 Entry curves

As shown in Exhibit 6-1, the entry curves are the set of one or more curves along the right curb (or edge of pavement) of the entry roadway leading into the circulatory roadway. It should not be confused with the entry path curve, defined by the radius of the fastest vehicular travel path through the entry geometry ($R_1$ on Exhibit 6-12).

The entry radius is an important factor in determining the operation of a roundabout as it has significant impacts on both capacity and safety. The entry radius, in conjunction with the entry width, the circulatory roadway width, and the central island geometry, controls the amount of deflection imposed on a vehicle’s entry path. Larger entry radii produce faster entry speeds and generally result in higher crash rates between entering and circulating vehicles. In contrast, the operational performance of roundabouts benefits from larger entry radii. As described in Chapter 4, British research has found that the capacity of an entry increases as its entry radius is increased (up to 20 m [65 ft], beyond which entry radius has little effect on capacity.

The entry curve is designed curvilinearly tangential to the outside edge of the circulatory roadway. Likewise, the projection of the inside (left) edge of the entry roadway should be curvilinearly tangential to the central island. Exhibit 6-24 shows a typical roundabout entrance geometry.

The primary objective in selecting a radius for the entry curve is to achieve the speed objectives, as described in Section 6.2.1. The entry radius should first produce an appropriate design speed on the fastest vehicular path. Second, it should desirably result in an entry path radius ($R_1$) equal to or less than the circulating path radius ($R_2$) (see Section 6.2.1.5).
6.3.5.1 Entry curves at single-lane roundabouts

For single-lane roundabouts, it is relatively simple to achieve the entry speed objectives. With a single traffic stream entering and circulating, there is no conflict between traffic in adjacent lanes. Thus, the entry radius can be reduced or increased as necessary to produce the desired entry path radius. Provided sufficient clearance is given for the design vehicle, approaching vehicles will adjust their path accordingly and negotiate through the entry geometry into the circulatory roadway.

Entry radii at urban single-lane roundabouts typically range from 10 to 30 m (33 to 98 ft). Larger radii may be used, but it is important that the radii not be so large as to result in excessive entry speeds. At local street roundabouts, entry radii may be below 10 m (33 ft) if the design vehicle is small.

At rural and suburban locations, consideration should be given to the speed differential between the approaches and entries. If the difference is greater than 20 km/h (12 mph), it is desirable to introduce approach curves or some other speed reduction measures to reduce the speed of approaching traffic prior to the entry curvature. Further details on rural roundabout design are provided in Section 6.5.

6.3.5.2 Entry curves at double-lane roundabouts

At double-lane roundabouts, the design of the entry curvature is more complicated. Overly small entry radii can result in conflicts between adjacent traffic streams. This conflict usually results in poor lane utilization of one or more lanes and significantly reduces the capacity of the approach. It can also degrade the safety performance as sideswipe crashes may increase. Techniques and guidelines for avoiding conflicts between adjacent entry lanes at double-lane roundabouts are provided in Section 6.4.
6.3.6 Exit curves

Exit curves usually have larger radii than entry curves to minimize the likelihood of congestion at the exits. This, however, is balanced by the need to maintain low speeds at the pedestrian crossing on exit. The exit curve should produce an exit path radius ($R_3$ in Exhibit 6-12) no smaller than the circulating path radius ($R_2$). If the exit path radius is smaller than the circulating path radius, vehicles will be traveling too fast to negotiate the exit geometry and may crash into the splitter island or into oncoming traffic in the adjacent approach lane. Likewise, the exit path radius should not be significantly greater than the circulating path radius to ensure low speeds at the downstream pedestrian crossing.

The exit curve is designed to be curvilinearly tangential to the outside edge of the circulatory roadway. Likewise, the projection of the inside (left) edge of the exit roadway should be curvilinearly tangential to the central island. Exhibit 6-25 shows a typical exit layout for a single-lane roundabout.

6.3.6.1 Exit curves at single-lane roundabouts

At single-lane roundabouts in urban environments, exits should be designed to enforce a curved exit path with a design speed below 40 km/h (25 mph) in order to maximize safety for pedestrians crossing the exiting traffic stream. Generally, exit radii should be no less than 15 m (50 ft). However, at locations with pedestrian activity and no large semi-trailer traffic, exit radii may be as low as 10 to 12 m (33 to 39 ft). This produces a very slow design speed to maximize safety and comfort for pedestrians. Such low exit radii should only be used in conjunction with similar or smaller entry radii on urban compact roundabouts with inscribed circle diameters below 35 m (115 ft).

In rural locations where there are few pedestrians, exit curvature may be designed with large radii, allowing vehicles to exit quickly and accelerate back to traveling speed. This, however, should not result in a straight path tangential to the central island because many locations that are rural today become urban in the future. Therefore, it is recommended that pedestrian activity be considered at all exits except where separate pedestrian facilities (paths, etc.) or other restrictions eliminate the likelihood of pedestrian activity in the foreseeable future.

6.3.6.2 Exit curves at double-lane roundabouts

As with the entries, the design of the exit curvature at double-lane roundabouts is more complicated than at single-lane roundabouts. Techniques and guidelines for avoiding conflicts between adjacent exit lanes at double-lane roundabouts are provided in Section 6.4.

6.3.7 Pedestrian crossing location and treatments

Pedestrian crossing locations at roundabouts are a balance among pedestrian convenience, pedestrian safety, and roundabout operations:

- **Pedestrian convenience**: Pedestrians want crossing locations as close to the intersection as possible to minimize out-of-direction travel. The further the crossing is from the roundabout, the more likely that pedestrians will choose a shorter route that may put them in greater danger.

- **Pedestrian safety**: Both crossing location and crossing distance are important. Crossing distance should be minimized to reduce exposure of pedestrian-vehicle conflicts. Pedestrian safety may also be compromised at a yield-line crosswalk because driver attention is directed to the left to look for gaps in the circulating traffic stream. Crosswalks should be located to take advantage of the splitter island; crosswalks located too far from the yield line require longer splitter islands. Crossings should also be located at distances away from the yield line measured in increments of approximate vehicle length to reduce the chance that vehicles will be queued across the crosswalk.
- **Roundabout operations:** Roundabout operations (primarily vehicular) can also be affected by crosswalk locations, particularly on the exit. A queuing analysis at the exit crosswalk may determine that a crosswalk location of more than one vehicle length away may be required to reduce to an acceptable level the risk of queuing into the circulatory roadway. Pedestrians may be able to distinguish exiting vehicles from circulating vehicles (both visually and audibly) at crosswalk locations further away from the roundabout, although this has not been confirmed by research.

With these issues in mind, pedestrian crossings should be designed as follows:

- The pedestrian refuge should be a minimum width of 1.8 m (6 ft) to adequately provide shelter for persons pushing a stroller or walking a bicycle (see Section 6.2.3).

- At single-lane roundabouts, the pedestrian crossing should be located one vehicle-length (7.5 m [25 ft]) away from the yield line. At double-lane roundabouts, the pedestrian crossing should be located one, two, or three car lengths (approximately 7.5 m, 15 m, or 22.5 m [25 ft, 50 ft, or 75 ft]) away from the yield line.

- The pedestrian refuge should be designed at street level, rather than elevated to the height of the splitter island. This eliminates the need for ramps within the refuge area, which can be cumbersome for wheelchairs.

- Ramps should be provided on each end of the crosswalk to connect the crosswalk to other crosswalks around the roundabout and to the sidewalk network.

- It is recommended that a detectable warning surface, as recommended in the Americans with Disabilities Act Accessibility Guidelines (ADAAG) §4.29 (Detectable Warnings), be applied to the surface of the refuge within the splitter island as shown in Exhibit 6-26. Note that the specific provision of the ADAAG requiring detectable warning surface at locations such as ramps and splitter islands (defined in the ADAAG as “hazardous vehicle areas”) has been suspended until July 26, 2001 (ADAAG §4.29.5). Where used, a detectable warning surface shall meet the following requirements (7):
  - The detectable warning surface shall consist of raised truncated domes with a nominal diameter of 23 mm (0.9 in), a nominal height of 5 mm (0.2 in), and a nominal center-to-center spacing of 60 mm (2.35 in).
  - The detectable warning surface shall contrast visually with adjoining surfaces, either light-on-dark or dark-on-light. The material used to provide contrast shall be an integral part of the walking surface.
  - The detectable warning surface shall begin at the curb line and extend into the pedestrian refuge area a distance of 600 mm (24 in). This creates a minimum 600-mm (24-in) clear space between detectable warning surfaces for a minimum splitter island width of 1.8 m (6 ft) at the pedestrian crossing. This is a deviation from the requirements of (suspended) ADAAG §4.29.5, which requires a 915-mm (36-in) surface width. However, this deviation is necessary to enable visually impaired pedestrians to distinguish the two interfaces with vehicular traffic.

In urban areas, speed tables (flat-top road humps) could be considered for wheelchair users, provided that good geometric design has reduced absolute vehicle
speeds to less than 20 km/h (12 mph) near the crossing. Pedestrian crossings across speed tables must have detectable warning material as described above to clearly delineate the edge of the street. Speed tables should generally be used only on streets with approach speeds of 55 km/h (35 mph) or less, as the introduction of a raised speed table in higher speed environments may increase the likelihood of single-vehicle crashes and is not consistent with the speed consistency philosophy presented in this document.

6.3.8 Splitter islands

Splitter islands (also called separator islands or median islands) should be provided on all roundabouts, except those with very small diameters at which the splitter island would obstruct the visibility of the central island. Their purpose is to provide shelter for pedestrians (including wheelchairs, bicycles, and baby strollers), assist in controlling speeds, guide traffic into the roundabout, physically separate entering and exiting traffic streams, and deter wrong-way movements. Additionally, splitter islands can be used as a place for mounting signs (see Chapter 7).

The splitter island envelope is formed by the entry and exit curves on a leg, as shown previously in Exhibits 6-24 and 6-25. The total length of the island should generally be at least 15 m (50 ft) to provide sufficient protection for pedestrians and to alert approaching drivers to the roundabout geometry. Additionally, the splitter island should extend beyond the end of the exit curve to prevent exiting traffic from accidentally crossing into the path of approaching traffic.

Exhibit 6-26 shows the minimum dimensions for a splitter island at a single-lane roundabout, including the location of the pedestrian crossing as discussed in Section 6.3.7.
While Exhibit 6-26 provides minimum dimensions for splitter islands, there are benefits to providing larger islands. Increasing the splitter island width results in greater separation between the entering and exiting traffic streams of the same leg and increases the time for approaching drivers to distinguish between exiting and circulating vehicles. In this way, larger splitter islands can help reduce confusion for entering motorists. A recent study by the Queensland Department of Main Roads found that maximizing the width of splitter islands has a significant effect on minimizing entering/circulating vehicle crash rates (2). However, increasing the width of the splitter islands generally requires increasing the inscribed circle diameter. Thus, these safety benefits may be offset by higher construction cost and greater land impacts.

Standard AASHTO guidelines for island design should be followed for the splitter island. This includes using larger nose radii at approach corners to maximize island visibility and offsetting curb lines at the approach ends to create a funneling effect. The funneling treatment also aids in reducing speeds as vehicles approach the roundabout. Exhibit 6-27 shows minimum splitter island nose radii and offset dimensions from the entry and exit traveled ways.
### 6.3.9 Stopping sight distance

Stopping sight distance is the distance along a roadway required for a driver to perceive and react to an object in the roadway and to brake to a complete stop before reaching that object. Stopping sight distance should be provided at every point within a roundabout and on each entering and exiting approach.

National Cooperative Highway Research Program (NCHRP) Report 400, *Determination of Stopping Sight Distances* (8), recommends the formula given in Equation 6-2 for determining stopping sight distance (presented in metric units, followed by a conversion of the equation to U.S. customary units).

\[
d = (0.278tV + 0.039)\frac{V^2}{a} \tag{6-2a, metric}
\]

where:
- \(d\) = stopping sight distance, m;
- \(t\) = perception-brake reaction time, assumed to be 2.5 s;
- \(V\) = initial speed, km/h; and
- \(a\) = driver deceleration, assumed to be 3.4 m/s\(^2\).

\[
d = (1.468tV + 1.087)\frac{V^2}{a} \tag{6-2b, metric}
\]

where:
- \(d\) = stopping sight distance, ft;
- \(t\) = perception-brake reaction time, assumed to be 2.5 s;
- \(V\) = initial speed, mph; and
- \(a\) = driver deceleration, assumed to be 11.2 ft/s\(^2\).

Exhibit 6-28 gives recommended stopping sight distances for design, as computed from the above equations.

<table>
<thead>
<tr>
<th>Speed (km/h)</th>
<th>Computed Distance* (m)</th>
<th>Speed (mph)</th>
<th>Computed Distance* (ft)</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>8.1</td>
<td>10</td>
<td>46.4</td>
</tr>
<tr>
<td>20</td>
<td>18.5</td>
<td>15</td>
<td>77.0</td>
</tr>
<tr>
<td>30</td>
<td>31.2</td>
<td>20</td>
<td>112.4</td>
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<tr>
<td>40</td>
<td>46.2</td>
<td>25</td>
<td>152.7</td>
</tr>
<tr>
<td>50</td>
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<td>60</td>
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<td>80</td>
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<td>90</td>
<td>155.5</td>
<td>50</td>
<td>427.2</td>
</tr>
<tr>
<td>100</td>
<td>184.2 *</td>
<td>55</td>
<td>496.7</td>
</tr>
</tbody>
</table>

Assumes 2.5 s perception-braking time, 3.4 m/s\(^2\) (11.2 ft/s\(^2\)) driver deceleration.
Stopping sight distance should be measured using an assumed height of driver’s eye of 1,080 mm (3.54 ft) and an assumed height of object of 600 mm (1.97 ft) in accordance with the recommendations to be adopted in the next AASHTO “Green Book” (8).

At roundabouts, three critical types of locations should be checked at a minimum:
- Approach sight distance (Exhibit 6-29);
- Sight distance on circulatory roadway (Exhibit 6-30); and
- Sight distance to crosswalk on exit (Exhibit 6-31).

Forward sight distance at entry can also be checked; however, this will typically be satisfied by providing adequate stopping sight distance on the circulatory roadway itself.


Exhibit 6-30. Sight distance on circulatory roadway.
6.3.10 Intersection sight distance

Intersection sight distance is the distance required for a driver without the right of way to perceive and react to the presence of conflicting vehicles. Intersection sight distance is achieved through the establishment of adequate sight lines that allow a driver to see and safely react to potentially conflicting vehicles. At roundabouts, the only locations requiring evaluation of intersection sight distance are the entries.

Intersection sight distance is traditionally measured through the determination of a sight triangle. This triangle is bounded by a length of roadway defining a limit away from the intersection on each of the two conflicting approaches and by a line connecting those two limits. For roundabouts, these “legs” should be assumed to follow the curvature of the roadway, and thus distances should be measured not as straight lines but as distances along the vehicular path.

Intersection sight distance should be measured using an assumed height of driver’s eye of 1,080 mm (3.54 ft) and an assumed height of object of 1,080 mm (3.54 ft) in accordance with the recommendations to be adopted in the next AASHTO “Green Book” (4).

Exhibit 6-32 presents a diagram showing the method for determining intersection sight distance. As can be seen in the exhibit, the sight distance “triangle” has two conflicting approaches that must be checked independently. The following two subsections discuss the calculation of the length of each of the approaching sight limits.
6.3.10.1 Length of approach leg of sight triangle
The length of the approach leg of the sight triangle should be limited to 15 m (49 ft). British research on sight distance determined that excessive intersection sight distance results in a higher frequency of crashes. This value, consistent with British and French practice, is intended to require vehicles to slow down prior to entering the roundabout, which allows them to focus on the pedestrian crossing prior to entry. If the approach leg of the sight triangle is greater than 15 m (49 ft), it may be advisable to add landscaping to restrict sight distance to the minimum requirements.

6.3.10.2 Length of conflicting leg of sight triangle
A vehicle approaching an entry to a roundabout faces conflicting vehicles within the circulatory roadway. The length of the conflicting leg is calculated using Equation 6-3:

\[ b = 0.278(V_{\text{major}})(t_c) \] (6-3a, metric)

where:

- \( b \) = length of conflicting leg of sight triangle, m
- \( V_{\text{major}} \) = design speed of conflicting movement, km/h, discussed below
- \( t_c \) = critical gap for entering the major road, s, equal to 6.5 s

\[ b = 1.468(V_{\text{major}})(t_c) \] (6-3b, U.S. customary)

where:

- \( b \) = length of conflicting leg of sight triangle, ft
- \( V_{\text{major}} \) = design speed of conflicting movement, mph, discussed below
- \( t_c \) = critical gap for entering the major road, s, equal to 6.5 s
Two conflicting traffic streams should be checked at each entry:

- **Entering stream**, comprised of vehicles from the immediate upstream entry. The speed for this movement can be approximated by taking the average of the entry path speed (path with radius $R_1$ from Exhibit 6-12) and the circulating path speed (path with radius $R_2$ from Exhibit 6-12).

- **Circulating stream**, comprised of vehicles that entered the roundabout prior to the immediate upstream entry. This speed can be approximated by taking the speed of left turning vehicles (path with radius $R_4$ from Exhibit 6-12).

The critical gap for entering the major road is based on the amount of time required for a vehicle to turn right while requiring the conflicting stream vehicle to slow no less than 70 percent of initial speed. This is based on research on critical gaps at stop-controlled intersections, adjusted for yield-controlled conditions (9). The critical gap value of 6.5 s given in Equation 6-3 is based on the critical gap required for passenger cars, which are assumed to be the most critical design vehicle for intersection sight distance. This assumption holds true for single-unit and combination truck speeds that are at least 10 km/h (6 mph) and 15 to 20 km/h (9 to 12 mph) slower than passenger cars, respectively.

<table>
<thead>
<tr>
<th>Conflicting Approach Speed (km/h)</th>
<th>Computed Distance (m)</th>
</tr>
</thead>
<tbody>
<tr>
<td>20</td>
<td>36.1</td>
</tr>
<tr>
<td>25</td>
<td>45.2</td>
</tr>
<tr>
<td>30</td>
<td>54.2</td>
</tr>
<tr>
<td>35</td>
<td>63.2</td>
</tr>
<tr>
<td>40</td>
<td>72.3</td>
</tr>
</tbody>
</table>

Exhibit 6-33. Computed length of conflicting leg of intersection sight triangle.

<table>
<thead>
<tr>
<th>Conflicting Approach Speed (mph)</th>
<th>Computed Distance (m)</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>95.4</td>
</tr>
<tr>
<td>15</td>
<td>143.0</td>
</tr>
<tr>
<td>20</td>
<td>190.1</td>
</tr>
<tr>
<td>25</td>
<td>238.6</td>
</tr>
<tr>
<td>30</td>
<td>286.3</td>
</tr>
</tbody>
</table>

Providing more than the minimum required intersection sight distance can lead to higher speeds that reduce intersection safety.

In general, it is recommended to provide no more than the minimum required intersection sight distance on each approach. Excessive intersection sight distance can lead to higher vehicle speeds that reduce the safety of the intersection for all road users (vehicles, bicycles, pedestrians). Landscaping can be effective in restricting sight distance to the minimum requirements.

Note that the stopping sight distance on the circulatory roadway (Exhibit 6-30) and the intersection sight distance to the circulating stream (Exhibit 6-32) imply restrictions on the height of the central island, including landscaping and other objects, within these zones. In the remaining central area of the central island, higher landscaping may serve to break the forward vista for through vehicles, thereby contributing to speed reduction. However, should errant vehicles encroach on the central island, Chapter 7 provides recommended maximum grades on the central island to minimize the probability of the vehicles rolling over, causing serious injury.
6.3.11 Vertical considerations

Elements of vertical alignment design for roundabouts include profiles, superelevation, approach grades, and drainage.

6.3.11.1 Profiles

The vertical design of a roundabout begins with the development of approach roadway and central island profiles. The development of each profile is an iterative process that involves tying the elevations of the approach roadway profiles into a smooth profile around the central island.

Generally, each approach profile should be designed to the point where the approach baseline intersects with the central island. A profile for the central island is then developed which passes through these four points (in the case of a four-legged roundabout). The approach roadway profiles are then readjusted as necessary to meet the central island profile. The shape of the central island profile is generally in the form of a sine curve. Examples of how the profile is developed can be found in Exhibits 6-34, 6-35, and 6-36, which consist of a sample plan, profiles on each approach, and a profile along the central island, respectively. Note that the four points where the approach roadway baseline intersects the central island baseline are identified on the central island profile.

Exhibit 6-34. Sample plan view.
Exhibit 6-35. Sample approach profile.

Exhibit 6-36. Sample central island profile.
6.3.11.2 Superelevation

As a general practice, a cross slope of 2 percent away from the central island should be used for the circulatory roadway. This technique of sloping outward is recommended for four main reasons:

- It promotes safety by raising the elevation of the central island and improving its visibility;
- It promotes lower circulating speeds;
- It minimizes breaks in the cross slopes of the entrance and exit lanes; and
- It helps drain surface water to the outside of the roundabout (2, 6).

The outward cross slope design means vehicles making through and left-turn movements must negotiate the roundabout at negative superelevation. Excessive negative superelevation can result in an increase in single-vehicle crashes and loss-of-load incidents for trucks, particularly if speeds are high. However, in the intersection environment, drivers will generally expect to travel at slower speeds and will accept the higher side force caused by reasonable adverse superelevation (10).

Exhibit 6-37 provides a typical section across the circulatory roadway of a roundabout without a truck apron. Exhibit 6-38 provides a typical section for a roundabout with a truck apron. Where truck aprons are used, the slope of the apron should be 3 to 4 percent; greater slopes may increase the likelihood of loss-of-load incidents.

**Exhibit 6-37.** Typical circulatory roadway section.

**Exhibit 6-38.** Typical section with a truck apron.
6.3.11.3 Locating roundabouts on grades

It is generally not desirable to locate roundabouts in locations where grades through the intersection are greater than four percent. The installation of roundabouts on roadways with grades lower than three percent is generally not problematic (6). At locations where a constant grade must be maintained through the intersection, the circulatory roadway may be constructed on a constant-slope plane. This means, for instance, that the cross slope may vary from +3 percent on the high side of the roundabout (sloped toward the central island) to -3 percent on the low side (sloped outward). Note that central island cross slopes will pass through level at a minimum of two locations for roundabouts constructed on a constant grade.

Care must be taken when designing roundabouts on steep grades. On approach roadways with grades steeper than -4 percent, it is more difficult for entering drivers to slow or stop on the approach. At roundabouts on crest vertical curves with steep approaches, a driver’s sight lines will be compromised, and the roundabout may violate driver expectancy. However, under the same conditions, other types of at-grade intersections often will not provide better solutions. Therefore, the roundabout should not necessarily be eliminated from consideration at such a location. Rather, the intersection should be relocated or the vertical profile modified, if possible.

6.3.11.4 Drainage

With the circulatory roadway sloping away from the central island, inlets will generally be placed on the outer curbline of the roundabout. However, inlets may be required along the central island for a roundabout designed on a constant grade through an intersection. As with any intersection, care should be taken to ensure that low points and inlets are not placed in crosswalks. If the central island is large enough, the designer may consider placing inlets in the central island.

6.3.12 Bicycle provisions

With regard to bicycle treatments, the designer should strive to provide bicyclists the choice of proceeding through the roundabout as either a vehicle or a pedestrian. In general, bicyclists are better served by treating them as vehicles. However, the best design provides both options to allow cyclists of varying degrees of skill to choose their more comfortable method of navigating the roundabout.

To accommodate bicyclists traveling as vehicles, bike lanes should be terminated in advance of the roundabout to encourage cyclists to mix with vehicle traffic. Under this treatment, it is recommended that bike lanes end 30 m (100 ft) upstream of the yield line to allow for merging with vehicles (11). This method is most successful at smaller roundabouts with speeds below 30 km/h (20 mph), where bicycle speeds can more closely match vehicle speeds.

To accommodate bicyclists who prefer not to use the circulatory roadway, a widened sidewalk or a shared bicycle/pedestrian path may be provided physically separated from the circulatory roadway (not as a bike lane within the circulatory...
6.3.13 Sidewalk treatments

Where possible, sidewalks should be set back from the edge of the circulatory roadway in order to discourage pedestrians from crossing to the central island, particularly when an apron is present or a monument on the central island. Equally important, the design should help pedestrians with visual impairments to recognize that they should not attempt to cross streets from corner to corner but at designated crossing points. To achieve these goals, the sidewalk should be designed so that pedestrians will be able to clearly find the intended path to the crosswalks. A recommended set back distance of 1.5 m (5 ft) (minimum 0.6 m [2 ft]) should be used, and the area between the sidewalk and curb can be planted with low shrubs or grass (see Chapter 7). Exhibit 6-40 shows this technique.

Exhibit 6-39. Possible provisions for bicycles.
6.3.14 Parking considerations and bus stop locations

Parking or stopping in the circulatory roadway is not conducive to proper roundabout operations and should be prohibited. Parking on entries and exits should also be set back as far as possible so as not to hinder roundabout operations or to impair the visibility of pedestrians. AASHTO recommends that parking should end at least 6.1 m (20 ft) from the crosswalk of an intersection (4). Curb extensions or “bulb-outs” can be used to clearly mark the limit of permitted parking and reduce the width of the entries and exits.

For safety and operational reasons, bus stops should be located as far away from entries and exits as possible, and never in the circulatory roadway.

- **Nearside stops**: If a bus stop is to be provided on the near side of a roundabout, it should be located far enough away from the splitter island so that a vehicle overtaking a stationary bus is in no danger of being forced into the splitter island, especially if the bus starts to pull away from the stop. If an approach has only one lane and capacity is not an issue on that entry, the bus stop could be located at the pedestrian crossing in the lane of traffic. This is not recommended for entries with more than one lane, because vehicles in the lane next to the bus may not see pedestrians.

- **Farside stops**: Bus stops on the far side of a roundabout should be constructed with pull-outs to minimize queuing into the roundabout. These stops should be located beyond the pedestrian crossing to improve visibility of pedestrians to other exiting vehicles.
6.3.15 Right-turn bypass lanes

In general, right-turn bypass lanes (or right-turn slip lanes) should be avoided, especially in urban areas with bicycle and pedestrian activity. The entries and exits of bypass lanes can increase conflicts with bicyclists. The generally higher speeds of bypass lanes and the lower expectation of drivers to stop increases the risk of collisions with pedestrians. However, in locations with minimal pedestrian and bicycle activity, right-turn bypass lanes can be used to improve capacity where there is heavy right turning traffic.

The provision of a right-turn bypass lane allows right-turning traffic to bypass the roundabout, providing additional capacity for the through and left-turn movements at the approach. They are most beneficial when the demand of an approach exceeds its capacity and a significant proportion of the traffic is turning right. However, it is important to consider the reversal of traffic patterns during the opposite peak time period. In some cases, the use of a right-turn bypass lane can avoid the need to build an additional entry lane and thus a larger roundabout. To determine if a right-turn bypass lane should be used, the capacity and delay calculations in Chapter 4 should be performed. Right-turn bypass lanes can also be used in locations where the geometry for right turns is too tight to allow trucks to turn within the roundabout.

Exhibit 6-41 shows an example of a right-turn bypass lane.
There are two design options for right-turn bypass lanes. The first option, shown in Exhibit 6-42, is to carry the bypass lane parallel to the adjacent exit roadway, and then merge it into the main exit lane. Under this option, the bypass lane should be carried alongside the main roadway for a sufficient distance to allow vehicles in the bypass lane and vehicles exiting the roundabout to accelerate to comparable speeds. The bypass lane is then merged at a taper rate according to AASHTO guidelines for the appropriate design speed. The second design option for a right-turn bypass lane, shown in Exhibit 6-43, is to provide a yield-controlled entrance onto the adjacent exit roadway. The first option provides better operational performance than the second does. However, the second option generally requires less construction and right-of-way than the first.

The option of providing yield control on a bypass lane is generally better for both bicyclists and pedestrians and is recommended as the preferred option in urban areas where pedestrians and bicyclists are prevalent. Acceleration lanes can be problematic for bicyclists because they end up being to the left of accelerating motor vehicles. In addition, yield control at the end of a bypass lane tends to slow motorists down, whereas an acceleration lane at the end of a bypass lane tends to promote higher speeds.

The radius of the right-turn bypass lane should not be significantly larger than the radius of the fastest entry path provided at the roundabout. This will ensure vehicle speeds on the bypass lane are similar to speeds through the roundabout, resulting in safe merging of the two roadways. Providing a small radius also provides greater safety for pedestrians who must cross the right-turn slip lane.
6.4 Double-Lane Roundabouts

While the fundamental principles described above apply to double-lane roundabouts as well as single-lane roundabouts, designing the geometry of double-lane roundabouts is more complicated. Because multiple traffic streams may enter, circulate through, and exit the roundabout side-by-side, consideration must be given to how these adjacent traffic streams interact with each other. Vehicles in adjacent entry lanes must be able to negotiate the roundabout geometry without competing for the same space. Otherwise, operational and/or safety deficiencies can occur.

6.4.1 The natural vehicle path

As discussed in Section 6.2.1, the fastest path through the roundabout is drawn to ensure the geometry imposes sufficient curvature to achieve a safe design speed. This path is drawn assuming the roundabout is vacant of all other traffic and the vehicle cuts across adjacent travel lanes, ignoring all lane markings. In addition to evaluating the fastest path, at double-lane roundabouts the designer must also evaluate the natural vehicle paths. This is the path an approaching vehicle will naturally take, assuming there is traffic in all approach lanes, through the roundabout geometry.
As two traffic streams approach the roundabout in adjacent lanes, they will be forced to stay in their lanes up to the yield line. At the yield point, vehicles will continue along their natural trajectory into the circulatory roadway, then curve around the central island, and curve again into the opposite exit roadway. The speed and orientation of the vehicle at the yield line determines its natural path. If the natural path of one lane interferes or overlaps with the natural path of the adjacent lane, the roundabout will not operate as safely or efficiently as possible.

The key principle in drawing the natural path is to remember that drivers cannot change the direction of their vehicle instantaneously. Neither can they change their speed instantaneously. This means that the natural path does not have sudden changes in curvature; it has transitions between tangents and curves and between consecutive reversing curves. Secondly, it means that consecutive curves should be of similar radius. If a second curve has a significantly smaller radius than the first curve, the driver will be traveling too fast to negotiate the turn and may lose control of the vehicle. If the radius of one curve is drawn significantly smaller than the radius of the previous curve, the path should be adjusted.

To identify the natural path of a given design, it may be advisable to sketch the natural paths over the geometric layout, rather than use a computer drafting program or manual drafting equipment. In sketching the path, the designer will naturally draw transitions between consecutive curves and tangents, similar to the way a driver would negotiate an automobile. Freehand sketching also enables the designer to feel how changes in one curve affect the radius and orientation of the next curve. In general, the sketch technique allows the designer to quickly obtain a smooth, natural path through the geometry that may be more difficult to obtain using a computer.

Exhibit 6-44 illustrates a sketched natural path of a vehicle through a typical double-lane roundabout.

Exhibit 6-44. Sketched natural paths through a double-lane roundabout.
6.4.2 Vehicle path overlap

Vehicle path overlap occurs when the natural path through the roundabout of one traffic stream overlaps the path of another. This can happen to varying degrees. It can reduce capacity, as vehicles will avoid using one or more of the entry lanes. It can also create safety problems, as the potential for sideswipe and single-vehicle crashes is increased. The most common type of path overlap is where vehicles in the left lane on entry are cut off by vehicles in the right lane, as shown in Exhibit 6-45.

Exhibit 6-45. Path overlap at a double-lane roundabout.

6.4.3 Design method to avoid path overlap

Achieving a reasonably low design speed at a double-lane roundabout while avoiding vehicle path overlap can be difficult because of conflicting interaction between the various geometric parameters. Providing small entry radii can produce low entry speeds, but often leads to path overlap on the entry, as vehicles will cut across lanes to avoid running into the central island. Likewise, providing small exit radii can aid in keeping circulating speeds low, but may result in path overlap at the exits.

6.4.3.1 Entry curves

At double-lane entries, the designer needs to balance the need to control entry speed with the need to minimize path overlap. This can be done a variety of ways that will vary significantly depending on site-specific conditions, and it is thus inappropriate to specify a single method for designing double-lane roundabouts. Regardless of the specific design method employed, the designer should maintain the overall design principles of speed control and speed consistency presented in Section 6.2.

One method to avoid path overlap on entry is to start with an inner entry curve that is curvilinearly tangential to the central island and then draw parallel alignments to determine the position of the outside edge of each entry lane. These curves can range from 30 to 60 m (100 to 200 ft) in urban environments and 40 to 80 m (130 to 260 ft) in rural environments. These curves should extend approximately 30 m (100
Another method to reduce entry speeds and avoid path overlap is to use a small-radius (generally 15 to 30 m [50 to 100 ft]) curve approximately 10 to 15 m (30 to 50 ft) upstream of the yield line. A second, larger-radius curve (or even a tangent) is then fitted between the first curve and the edge of the circulatory roadway. In this way, vehicles will still be slowed by the small-radius approach curve, and they will be directed along a path that is tangential to the central island at the time they reach the yield line. Exhibit 6-47 demonstrates this alternate method of design.
As in the case of single-lane roundabouts, it is a primary objective to ensure that the entry path radius along the fastest path is not substantially larger than the circulating path radius. Referring to Exhibit 6-12, it is desirable for \( R_1 \) to be less than or approximately equal to \( R_2 \). At double-lane roundabouts, however, \( R_1 \) should not be excessively small. If \( R_1 \) is too small, vehicle path overlap may result, reducing the operational efficiency and increasing potential for crashes. Values for \( R_1 \) in the range of 40 to 70 m (130 to 230 ft) are generally preferable. This results in a design speed of 35 to 45 km/h (22 to 28 mph).

The entry path radius, \( R_1 \), is controlled by the offset between the right curb line on the entry roadway and the curb line of the central island (on the driver’s left). If the initial layout produces an entry path radius above the preferred design speed, one way to reduce it is to gradually shift the approach to the left to increase the offset; however, this may increased adjacent exit speeds. Another method to reduce the entry path radius is to move the initial, small-radius entry curve closer to the circulatory roadway. This will decrease the length of the second, larger-radius curve and increase the deflection for entering traffic. However, care must be taken to ensure this adjustment does not produce overlapping natural paths.

### 6.4.3.2 Exit curves

To avoid path overlap on the exit, it is important that the exit radius at a double-lane roundabout not be too small. At single-lane roundabouts, it is acceptable to use a minimal exit radius in order to control exit speeds and maximize pedestrian safety. However, the same is not necessarily true at double-lane roundabouts. If the exit radius is too small, traffic on the inside of the circulatory roadway will tend to exit into the outside exit lane on a more comfortable turning radius.

At double-lane roundabouts in urban environments, the principle for maximizing pedestrian safety is to reduce vehicle speeds prior to the yield and maintain similar (or slightly lower) speeds within the circulatory roadway. At the exit points, traffic will still be traveling slowly, as there is insufficient distance to accelerate significantly. If the entry and circulating path radii (\( R_1 \) and \( R_2 \), as shown on Exhibit 6-12) are each 50 m (165 ft), exit speeds will generally be below 40 km/h (25 mph) regardless of the exit radius.

To achieve exit speeds slower than 40 km/h (25 mph), as is often desirable in environments with significant pedestrian activity, it may be necessary to tighten the exit radius. This may improve safety for pedestrians at the possible expense of increased vehicle-vehicle collisions.

### 6.5 Rural Roundabouts

Roundabouts located on rural roads often have special design considerations because approach speeds are higher than urban or local streets and drivers generally do not expect to encounter speed interruptions. The primary safety concern in rural locations is to make drivers aware of the roundabout with ample distance to comfortably decelerate to the appropriate speed. This section provides design guidelines for providing additional speed-reduction measures on rural roundabout approaches.
6.5.1 Visibility

Perhaps the most important element affecting safety at rural intersections is the visibility of the intersection itself. Roundabouts are no different from stop-controlled or signalized intersections in this respect except for the presence of curbing along roadways that are typically not curbed. Therefore, although the number and severity of multiple-vehicle collisions at roundabouts may decrease (as discussed previously), the number of single-vehicle crashes may increase. This potential can be minimized with attention to proper visibility of the roundabout and its approaches.

Where possible, the geometric alignment of approach roadways should be constructed to maximize the visibility of the central island and the general shape of the roundabout. Where adequate visibility cannot be provided solely through geometric alignment, additional treatments (signing, pavement markings, advanced warning beacons, etc.) should be considered (see Chapter 7). Note that many of these treatments are similar to those that would be applied to rural stop-controlled or signalized intersections.

6.5.2 Curbing

On an open rural highway, changes in the roadway’s cross-section can be an effective means to help approaching drivers recognize the need to reduce their speed. Rural highways typically have no outside curbs with wide paved or gravel shoulders. Narrow shoulder widths and curbs on the outside edges of pavement, on the other hand, generally give drivers a sense they are entering a more urbanized setting, causing them to naturally slow down. Thus, consideration should be given to reducing shoulder widths and introducing curbs when installing a roundabout on an open rural highway.

Curbs help to improve delineation and to prevent “corner cutting,” which helps to ensure low speeds. In this way, curbs help to confine vehicles to the intended design path. The designer should carefully consider all likely design vehicles, including farm equipment, when setting curb locations. Little research has been performed to date regarding the length of curbing required in advance of a rural roundabout. In general, it may be desirable to extend the curbing from the approach for at least the length of the required deceleration distance to the roundabout.

6.5.3 Splitter islands

Another effective cross-section treatment to reduce approach speeds is to use longer splitter islands on the approaches (10). Splitter islands should generally be extended upstream of the yield bar to the point at which entering drivers are expected to begin decelerating comfortably. A minimum length of 60 m (200 ft) is recommended (10). Exhibit 6-48 provides a diagram of such a splitter island design. The length of the splitter island may differ depending upon the approach speed. The AASHTO recommendations for required braking distance with an alert driver should be applied to determine the ideal splitter island length for rural roundabout approaches.

A further speed-reduction technique is the use of landscaping on the extended splitter island and roadside to create a “tunnel” effect. If such a technique is used, the stopping and intersection sight distance requirements (sections 6.3.9 and 6.3.10) will dictate the maximum extent of such landscaping.
6.5.4 Approach curves

Roundabouts on high-speed roads (speeds of 80 km/h [50 mph] or higher), despite extra signing efforts, may not be expected by approaching drivers, resulting in erratic behavior and an increase in single-vehicle crashes. Good design encourages drivers to slow down before reaching the roundabout, and this can be most effectively achieved through a combination of geometric design and other design treatments (see Chapter 7). Where approach speeds are high, speed consistency on the approach needs to be addressed to avoid forcing all of the reduction in speed to be completed through the curvature at the roundabout.

The radius of an approach curve (and subsequent vehicular speeds) has a direct impact on the frequency of crashes at a roundabout. A study in Queensland, Australia, has shown that decreasing the radius of an approach curve generally decreases the approaching rear-end vehicle crash rate and the entering-circulating and exiting-circulating vehicle crash rates (see Chapter 5). On the other hand, decreasing the radius of an approach curve may increase the single-vehicle crash rate on the curve, particularly when the required side-friction for the vehicle to maintain its path is too high. This may encourage drivers to cut across lanes and increase sideswipe crash rates on the approach. It is recommended that approach speeds immediately prior to the entry curves of the roundabout be limited to 60 km/h (37 mph) to minimize high-speed rear-end and entering-circulating vehicle crashes.

One method to achieve speed reduction that reduces crashes at the roundabout while minimizing single-vehicle crashes is the use of successive curves on approaches. The study in Queensland, Australia, found that by limiting the change in 85th-percentile speed on successive geometric elements to 20 km/h (12 mph), the crash rate was reduced. It was found that the use of successive reverse curves prior to the roundabout approach curve reduced the single-vehicle crash rate and the sideswipe crash rate on the approach. It is recommended that approach speeds immediately prior to the entry curves of the roundabout be limited to 60 km/h (37 mph) to minimize high-speed rear-end and entering-circulating vehicle crashes.
Exhibit 6-49 shows a typical rural roundabout design with a succession of three curves prior to the yield line. As shown in the exhibit, these approach curves should be successively smaller radii in order to minimize the reduction in design speed between successive curves. The aforementioned Queensland study found that shifting the approaching roadway laterally by 7 m (23 ft) usually enables adequate curvature to be obtained while keeping the curve lengths to a minimum. If the lateral shift is too small, drivers are more likely to cut into the adjacent lane (2).

Exhibit 6-49, Use of successive curves on high speed approaches.

Equations 6-4 and 6-5 can be used to estimate the operating speed of two-lane rural roads as a function of degree of curvature. Equation 6-6 can be used similarly for four-lane rural roads (13).

Two-lane rural roads:

\[
V_{85} = 103.66 - 1.95D, D \geq 3^\circ
\]

\[
V_{85} = 97.9, D < 3^\circ
\]

where: \( V_{85} = \) 85th-percentile speed, km/h (1 km/h = 0.621 mph); and \( D = \) degree of curvature, degrees = \( \frac{1746.38}{R} \)

\( R = \) radius of curve, m

Four-lane rural roads:

\[
V_{85} = 103.66 - 1.95D
\]

where: \( V_{85} = \) 85th-percentile speed, km/h (1 km/h = 0.621 mph); and \( D = \) degree of curvature, degrees = \( \frac{1746.38}{R} \)

\( R = \) radius of curve, m

6.6 Mini-Roundabouts

As discussed in Chapter 1, a mini-roundabout is an intersection design alternative that can be used in place of stop control or signalization at physically constrained intersections to help improve safety problems and excessive delays at minor approaches. Mini-roundabouts are not traffic calming devices but rather are a form of roundabout intersection. Exhibit 6-50 presents an example of a mini-roundabout.
Mini-roundabouts should only be considered in areas where all approaching roadways have an 85th-percentile speed of less than 50 km/h (30 mph). In addition, mini-roundabouts are not recommended in locations in which high U-turn traffic is expected, such as at the ends of street segments with access restrictions. Mini-roundabouts are not well suited for high volumes of trucks, as trucks will occupy most of the intersection when turning.

The design of the central island of a mini-roundabout is defined primarily by the requirement to achieve speed reduction for passenger cars. As discussed previously in Section 6.2, speed reduction for entering vehicles and speed consistency with circulating vehicles are important. Therefore, the location and size of the central island are dictated by the inside of the swept paths of passenger cars that is needed to achieve a maximum recommended entry speed of 25 km/h (15 mph).

The central island of a mini-roundabout is typically a minimum of 4 m (13 ft) in diameter and is fully mountable by large trucks and buses. Composed of asphalt, concrete, or other paving material, the central island should be domed at a height of 25 to 30 mm per 1 m diameter (0.3 to 0.36 in per 1 ft diameter), with a maximum height of 125 mm (5 in) (14). Although fully mountable and relatively small, it is essential that the central island be clear and conspicuous (14, 15). Chapter 7 provides a sample signing and striping planing plan for mini-roundabout.

The outer swept path of passenger cars and large vehicles is typically used to define the location of the yield line and boundary of each splitter island with the circulatory roadway. Given the small size of a mini-roundabout, the outer swept path of large vehicles may not be coincident with the inscribed circle of the roundabout, which is defined by the outer curbs. Therefore, the splitter islands and yield line may extend into the inscribed circle for some approach geometries. On the other hand, for very small mini-roundabouts, such as the one shown in Exhibit 6-50, all turning trucks will pass directly over the central island while not encroaching on the circulating roadway to the left which may have opposing traffic. In these cases, the yield line and splitter island should be set coincident with the inscribed
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This chapter presents guidelines on the design of traffic elements, illumination, and landscaping associated with roundabouts. The design of these elements is critical in achieving the desired operational and safety features of a roundabout, as well as the desired visibility and aesthetics. This chapter is divided into the following sections:

- Signing;
- Pavement Markings;
- Illumination;
- Work Zone Traffic Control; and
- Landscaping.

### 7.1 Signing

The overall concept for roundabout signing is similar to general intersection signing. Proper regulatory control, advance warning, and directional guidance are required to avoid driver expectancy related problems. Signs should be located where they have maximum visibility for road users but a minimal likelihood of even momentarily obscuring pedestrians as well as motorcyclists and bicyclists, who are the most vulnerable of all roundabout users. Signing needs are different for urban and rural applications and for different categories of roundabouts.

#### 7.1.1 Relationship with the Manual on Uniform Traffic Control Devices

The *Manual on Uniform Traffic Control Devices for Streets and Highways* (MUTCD) (1) and *Standard Highway Signs* (2), as well as local applicable standards, govern the design and placement of signs. To the extent possible, this guide has been prepared in accordance with the 1988 edition of the MUTCD. However, roundabouts present a number of new signing issues that are not addressed in the 1988 edition. For this reason, a number of new signs or uses for existing signs have been introduced that are under consideration for inclusion in the next edition of the MUTCD. Until such signs or uses are formally adopted, these recommendations should be considered provisional and are subject to MUTCD Section 1A-6, “Manual Changes, Interpretations and Authority to Experiment.”

The following signs and applications recommended below are subject to these conditions:

- Use of YIELD signs on more than one approach to an intersection (Section 7.1.2.1);
- Long chevron plate (Section 7.1.2.2);
- Roundabout Ahead sign (Section 7.1.3.1);
- Advance diagrammatic guide signs (Section 7.1.4.1); and
- Exit guide signs (Section 7.1.4.2).
7.1.2 Regulatory signs

A number of regulatory signs are appropriate for roundabouts and are described below.

7.1.2.1 YIELD sign

A YIELD sign (R1-2), shown in Exhibit 7-1, is required at the entrance to the roundabout. For single-lane approaches, one YIELD sign placed on the right side is sufficient, although a second YIELD sign mounted in the splitter island on the left side of the approach may be used. For approaches with more than one lane, the designer should place YIELD signs on both the left and right sides of the approach. This practice is consistent with the recommendations of the MUTCD on the location of STOP and YIELD signs on single-lane and multilane approaches (MUTCD, §2B-9). To prevent circulating vehicles from yielding unnecessarily, the face of the yield sign should not be visible from the circulatory roadway. YIELD signs may also be used at the entrance to crosswalks on both the entry and exit legs of an approach. However, the designer should not use both YIELD signs and Pedestrian Crossing signs (see Section 7.1.3.5) to mark a pedestrian crossing, as the yield signs at the roundabout entrance may be obscured.

Exhibit 7-1. YIELD sign (R1-2).

7.1.2.2 ONE WAY sign

ONE WAY signs (R6-1R) may be used in the central island opposite the entrances. An example is shown in Exhibit 7-2. The ONE WAY sign may be supplemented with chevron signs to emphasize the direction of travel within the circulatory roadway (see Section 7.1.3.4).

At roundabouts with one-way streets on one or more approaches, the use of a regulatory ONE WAY sign may be confusing. In these cases, a Large Arrow warning sign (see Section 7.1.3.3) may be used.

Exhibit 7-2. ONE WAY sign (R6-1R).

7.1.2.3 KEEP RIGHT sign

KEEP RIGHT signs (R4-7 or text variations R4-7a and R4-7b) should be used at the nose of all nonmountable splitter islands. This sign is shown in Exhibit 7-3.

For small splitter islands, a Type 1 object marker may be substituted for the KEEP RIGHT sign. This may reduce sign clutter and improve the visibility of the YIELD sign.

Exhibit 7-3. KEEP RIGHT sign (R4-7).
7.1.2.4 Lane-use control signs

For roundabouts with multiple entry lanes, it can often be confusing for unfamiliar drivers to know which lanes to use for the various left, through, and right movements. There is no international consensus on the effectiveness of lane-use signs and/or pavement markings.

The designation of lanes on entry to a roundabout is directly related to a number of factors:

- **Traffic volume balance.** Roundabouts with especially heavy left- or right-turning traffic may require more than one lane to handle the expected demand (see Chapter 4).

- **Exit lane requirements.** In general, the number of exit lanes provided should be the minimum required to handle the expected exit volume. This may not correspond with the number of entry lanes on the opposite side of the roundabout that would use the exit as through vehicles (see Chapter 4).

- **The rules of the road.** Drivers have a reasonable expectation that multiple through lanes entering a roundabout will have an equal number of receiving lanes on exit on the far side of the roundabout (see Chapter 2).

Lane-use control signs are generally not recommended wherever possible, at least until drivers become more accustomed to driving roundabouts.
7.1.3 Warning signs

A number of warning signs are appropriate for roundabouts and are described below. The amount of warning a motorist needs is related to the intersection setting and the vehicular speeds on approach roadways. The specific placement of warning signs is governed by the applicable sections of the MUTCD.
7.1.3.1 *Circular Intersection sign*

A Circular Intersection sign (W2-6) may be installed on each approach in advance of the roundabout. This sign, given in Exhibit 7-6, is proposed as part of the next edition of the MUTCD. When used, it is recommended that this sign be modified to reflect the number and alignment of approaches.

Exhibit 7-6. Circular Intersection sign (W2-6).

It is also recommended that an advisory speed plate (W13-1) be used with this sign, as shown in Exhibit 7-7. The speed given on the advisory speed plate should be no higher than the design speed of the circulatory roadway, as determined in Chapter 6.

Exhibit 7-7. Advisory speed plate (W13-1).

An alternative to the Circular Intersection sign, called a Roundabout Ahead sign, has been proposed and is shown in Exhibit 7-8. The rationale for this sign is given in Appendix C. At a minimum it is recommended that the Roundabout Ahead sign be used in place of the Circular Intersection sign at mini-roundabouts (see Section 7.1.7).

Exhibit 7-8. Roundabout Ahead sign.

7.1.3.2 *YIELD AHEAD sign*

A YIELD AHEAD sign (W3-2 or W3-2a) should be used on all approaches to a roundabout in advance of the yield sign. These signs provide drivers with advance warning that a YIELD sign is approaching. The preferred symbolic form of this sign is shown in Exhibit 7-9.

YIELD AHEAD signs warn drivers of the upcoming YIELD sign.

Exhibit 7-9. YIELD AHEAD sign (W3-2a).
7.1.3.3 Large Arrow sign
A Large Arrow sign with a single arrow pointing to the right (W1-6) should be used in the central island opposite the entrances, unless a regulatory ONE-WAY sign has been used. The Large Arrow sign is shown in Exhibit 7-10.

Chevron plates can be especially useful for nighttime visibility for sites without illumination.

7.1.3.4 Chevron Plate
The Large Arrow may be supplemented or replaced by a long chevron board (W1-8a, as proposed in the next edition of the MUTCD) to emphasize the direction of travel within the circulatory roadway.

7.1.3.5 Pedestrian Crossing
Pedestrian Crossing signs (W11-2a) may be used at pedestrian crossings within a roundabout at both entries and exits. Pedestrian Crossing signs should be used at all pedestrian crossings at double-lane entries, double-lane exits, and right-turn bypass lanes. This sign is shown in Exhibit 7-12.

The use of Pedestrian Crossing signs is dependent on the specific laws of the governing state. If the crosswalk at a roundabout is not considered to be part of the intersection and is instead considered a marked midblock crossing, Pedestrian Crossing signs are required. Where installed, Pedestrian Crossing signs should be located in such a way to not obstruct view of the YIELD sign.
7.1.4 Guide signs

Guide signs are important in providing drivers with proper navigational information. This is especially true at roundabouts where out-of-direction travel may disorient unfamiliar drivers. A number of guide signs are appropriate for roundabouts and are described below.

7.1.4.1 Advance destination guide signs

Advance destination guide signs should be used in all rural locations and in urban/suburban areas where appropriate. The sign should be either a destination sign using text (D1-3) or using diagrams. Examples of both are shown in Exhibit 7-13. Diagrammatic signs are preferred because they reinforce the form and shape of the approaching intersection and make it clear to the driver how they are expected to navigate the intersection. Advance destination guide signs are not necessary at local street roundabouts or in urban settings where the majority of traffic tends to be familiar with the site.

The circular shape in a diagrammatic sign provides an important visual cue to all users of the roundabout.

Exhibit 7-13. Examples of advance destination guide signs.

Diagrammatic Style (Preferred)

Leeds, MD

Taneytown, MD

Lothian, MD

Long Beach, CA
7.1.4.2 Exit guide signs

Exit guide signs (D1-1) are recommended to designate the destinations of each exit from the roundabout. These signs are conventional intersection direction signs or directional route marker assemblies and can be placed either on the right-hand side of the roundabout exit or in the splitter island. An example is shown in Exhibit 7-14.

Exhibit 7-14. Exit guide sign (D1-1).

Exit guide signs reduce the potential for disorientation.

The designer needs to balance the need for adequate signing with the tendency to use too many signs.

7.1.4.3 Route confirmation signs

For roundabouts involving the intersection of one or more numbered routes, route confirmation assemblies should be installed directly after the roundabout exit. These provide drivers with reassurance that they have selected the correct exit at the roundabout. These assemblies should be located no more than 30 m (100 ft) beyond the intersection in urban areas and 60 m (200 ft) beyond the intersection in rural areas.

7.1.5 Urban signing considerations

The amount of signing required at individual locations is largely based on engineering judgment. However, in practice, the designer can usually use fewer and smaller signs in urban settings than in rural settings. This is true because drivers are generally traveling at lower vehicular speeds and have higher levels of familiarity at urban intersections. Therefore, in many urban settings the advance destination guide signs can be eliminated. However, some indication of street names should be included in the form of exit guide signs or standard street name signs. Another consideration in urban settings is the use of minimum amounts of signing to avoid sign clutter. A sample signing plan for an urban application is shown in Exhibit 7-15.
Exhibit 7-15. Sample signing plan for an urban roundabout.
7.1.6 Rural and suburban signing considerations

Rural and suburban conditions are characterized by higher approach speeds. Route guidance tends to be focused more on destinations and numbered routes rather than street names. A sample signing plan for a rural application is shown in Exhibit 7-16.

Exhibit 7-16. Sample signing plan for a rural roundabout.
In cases where high speeds are expected (in excess of 80 km/h [50 mph]) and the normal signage and geometric features are not expected to produce the desired reduction in vehicle speeds, the following measures may also be considered (examples of some of these treatments are given in Exhibit 7-17):

- Large advance warning signs;
- Addition of hazard identification beacons to approach signing;
- Use of rumble strips in advance of the roundabout;
- Pavement marking across pavement; and
- Use of speed warning signs. These can be triggered by speeds exceeding an acceptable threshold.

These speed reduction treatments can apply to all intersection types, not just roundabouts.

Exhibit 7-17. Examples of speed reduction treatments.

Warning beacons. Leeds, MD

Rumble strips. Cearfoss, MD

Speed warning signs. Leeds, MD

7.1.7 Mini-roundabout signing considerations

Due to their small size and unique features, mini-roundabouts require a somewhat different signing treatment than the larger urban roundabouts. The principal differences in signing at mini-roundabouts as compared to other urban roundabouts are the following:

- The central island is fully mountable. Therefore, no ONE WAY signs, Large Arrow signs, or chevrons can be located there. It is recommended that the direction of circulation be positively indicated through the use of pavement markings, as discussed in Section 7.2.4.

- The splitter islands are either painted or are fully mountable. Therefore, KEEP RIGHT signs are not appropriate for mini-roundabouts.
Typically, advance directional guide signs and exit guide signs are unnecessary, given the size of the mini-roundabout and the nature of the approach roadways (generally low-speed local streets). However, standard street name signs (D3) should be used.

The Roundabout Ahead warning sign discussed in Section 7.1.3.1 should be used on each approach in advance of the YIELD sign. The Circular Intersection warning gives no indication of the direction of circulation required at the mini-roundabout.

Exhibit 7-18 gives a sample signing plan for a mini-roundabout.

Exhibit 7-18. Sample signing plan for a mini-roundabout.
7.2 Pavement Markings

Typical pavement markings for roundabouts consist of delineating the entries and the circulatory roadway.

7.2.1 Relationship with the Manual on Uniform Traffic Control Devices

As with signing, the MUTCD (1) and applicable local standards govern the design and placement of pavement markings. Roundabouts present a number of new pavement marking issues that are not addressed in the 1988 edition of the MUTCD. For this reason, a number of new pavement markings or uses for existing pavement markings have been introduced that are under consideration for inclusion in the next edition of the MUTCD. Until such pavement markings or uses are formally adopted, these recommendations should be considered provisional and are subject to MUTCD Section 1A-6, “Manual Changes, Interpretations and Authority to Experiment.”

The following pavement markings and applications recommended below are subject to these conditions:

- YIELD lines (Section 7.2.2.1); and
- Symbolic YIELD legend (Section 7.2.2.2).

7.2.2 Approach and entry pavement markings

Approach and entry pavement markings consist of yield lines, pavement word and symbol markings, and channelization markings. In addition, multilane approaches require special attention to pavement markings. The following sections discuss these in more detail.

7.2.2.1 Yield lines

Yield lines should be used to demarcate the entry approach from the circulatory roadway. Yield lines should be located along the inscribed circle at all roundabouts except mini-roundabouts (see Section 7.2.4). No yield lines should be placed to demarcate the exit from the circulatory roadway.

The MUTCD currently provides no standard for yield lines. The recommended yield line pavement marking is a broken line treatment consisting of 400-mm (16-in) wide stripes with 1-m (3-ft) segments and 1-m (3-ft) gaps. This type of yield line is the simplest to install.

Alternatively, several European countries use a yield line marking consisting of a series of white triangles (known as “shark’s teeth”). These markings tend to be more visible to approaching drivers. Exhibit 7-19 presents examples of broken line and “shark’s teeth” yield line applications. The “shark’s teeth” ahead of the broken line has been recommended for adoption in the next edition of the MUTCD.

Yield lines provide a visual separation between the approach and the circulatory roadway.

“Shark’s teeth” provide more visual “punch” but require a new template for installation.
7.2.2.2 Pavement word and symbol markings

In some cases, the designer may want to consider pavement word or symbol markings to supplement the signing and yield line marking. This typically consists of the word YIELD painted on the entrance to the roundabout immediately prior to the yield line. These markings should conform to the standards given in the appropriate section of the MUTCD (§3B-20).

Alternatively, some European countries paint a symbolic yield sign upstream of the yield line. This treatment has the advantage of being symbolic; however, such a treatment has not seen widespread use in the United States to date.

7.2.2.3 Lane-use control markings

If lane-use control signing has been used to designate specific lane use on an approach with more than one lane, it is recommended that corresponding arrow legends be used within each lane. See Section 7.1.2.4 for more discussion of the use of lane-use controls.

7.2.2.4 Approach markings

Typically, pavement markings are provided around raised splitter islands and right-turn bypass islands to enhance driver recognition of the changing roadway. Channelization markings shall be yellow when to the left of the traffic stream and white when to the right of the traffic stream. For a roundabout splitter island, pavement markings shall be yellow adjacent to the entry and exit and white adjacent to the circulatory roadway. Exhibit 7-20 presents a recommended pavement marking plan for the channelization on a typical single-lane approach to a roundabout. Optionally, edge stripes may end at the points of the splitter islands, allowing the curbs themselves to provide edge delineation.

Raised pavement markers are generally recommended for supplementing pavement markings. These have the benefit of additional visibility at night and in inclement weather. However, they increase maintenance costs and can be troublesome in areas requiring frequent snow removal. In addition, raised pavement markers should not be used in the path of travel of bicycles.
For small splitter islands (in area less than 7 m² [75 ft²]), the island may consist of pavement markings only. However, where possible, curbed splitter islands should be used.

### 7.2.2.5 Pedestrian crosswalk markings

Pedestrian crosswalk markings should generally be installed at all pedestrian crossing locations within roundabouts in urban locations. Because the crosswalk at a roundabout is located away from the yield line, it is important to channelize pedestrians to the appropriate crossing location. These markings should not be construed as a safety device, as data from other countries suggest that the presence of markings has no appreciable effect on pedestrian safety. Rather, markings provide guidance for pedestrians in navigating a roundabout and provide a visual cue to drivers of where pedestrians may be within the roadway. The use of crosswalk markings in this manner is consistent with published recommendations (3). Marked crosswalks are generally not needed at locations where the crosswalk is distinguished from the roadway by visually contrasting pavement colors and textures.

A crosswalk marking using a series of lines parallel to the flow of traffic (known as a “zebra crosswalk”) is recommended. These lines should be approximately 0.3 m to 0.6 m (12 in to 24 in) wide, spaced 0.3 m to 1.0 m (12 in to 36 in) apart, and span the width of the crosswalk (similar to the recommendations in MUTCD §3B-18). Crosswalk markings should be installed across both the entrance and exit of each leg and across any right turn bypass lanes. The crosswalk should be aligned with

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**Exhibit 7-20.** Approach pavement markings.
the ramps and pedestrian refuge in the splitter island and have markings that are generally perpendicular to the flow of vehicular traffic.

The zebra crosswalk has a number of advantages over the traditional transverse crosswalk marking in roundabout applications:

- Because the crosswalk at a roundabout is set back from the yield line, the zebra crosswalk provides a higher degree of visibility.
- The zebra crosswalk is distinct from traditional transverse crosswalk markings typically used at signalized intersections, thus alerting both drivers and pedestrians that this intersection is different from a signalized intersection.
- The zebra crosswalk is also less likely to be confused with the yield line than a transverse crosswalk.
- Although the initial cost is somewhat higher, the zebra crossing may require less maintenance due to the ability to space the markings to avoid vehicle tire tracks.

In rural locations where pedestrian activity is expected to be minimal, pedestrian crosswalk markings are optional. Pedestrian crosswalk markings should not be used at roundabouts without illumination (see Section 7.3 for an identification of these cases) because the headlights of vehicles may not be sufficient to illuminate a pedestrian in time to avoid a collision (4). Regardless of whether the crosswalk is marked, all roundabouts with any reasonable possibility of pedestrian activity should have geometric features to accommodate pedestrians as described in Chapter 6.

In addition to pavement markings, flashing warning lights mounted in the pavement and activated by a pedestrian push button or other method may be considered. These are not part of the current MUTCD and thus must be treated as an experimental traffic control device (see Section 7.2.1).

7.2.2.6 Bike lane markings

Bicycle striping treatments should be used when an existing (or proposed) bike lane is part of the roadway facility. Exhibit 7-20 shows a recommended treatment for bike lanes on an approach to a roundabout.

7.2.3 Circulatory roadway pavement markings

In general, lane lines should not be striped within the circulatory roadway, regardless of the width of the circulatory roadway. Circulatory lane lines can be misleading in that they may provide drivers a false sense of security.

In addition, bike lane markings within the circulatory roadway are not recommended. The additional width of a bike lane within the circulatory roadway increases vehicular speed and increases the probability of motor vehicle-cyclist crashes. Bicyclists should circulate with other vehicles, travel through the roundabout as a pedestrian on the sidewalk, or use a separate shared-use pedestrian and bicycle facility where provided.
7.2.4 Mini-roundabout pavement markings

Mini-roundabouts require pavement marking treatments that are somewhat different from other urban roundabouts. The following pavement marking treatments are recommended for mini-roundabouts.

- Pavement marking arrows should be provided in the circulatory roadway in front of each entry to indicate the direction of circulation. As noted in the discussion of signing treatments (Section 7.1.7), no signs can be placed in the fully mountable central island.

- At a minimum, the edges of the mountable central island and splitter islands should be painted to improve their visibility.

A sample pavement marking plan for a mini-roundabout is given in Exhibit 7-21.

Exhibit 7-21. Sample pavement marking plan for a mini-roundabout.
7.3 Illumination

For a roundabout to operate satisfactorily, a driver must be able to enter the roundabout, move through the circulating traffic, and separate from the circulating stream in a safe and efficient manner. To accomplish this, a driver must be able to perceive the general layout and operation of the intersection in time to make the appropriate maneuvers. Adequate lighting should therefore be provided at all roundabouts. Exhibit 7-22 shows an example of an illuminated roundabout at night.

Exhibit 7-22. Illumination of a roundabout.

Loveland, CO

73.1 Need for illumination

The need for illumination varies somewhat based on the location in which the roundabout is located.

73.1.1 Urban conditions

In urban settings, illumination should be provided for the following reasons:

- Most if not all approaches are typically illuminated.
- Illumination is necessary to improve the visibility of pedestrians and bicyclists.

73.1.2 Suburban conditions

For roundabouts in suburban settings, illumination is recommended. For safety reasons, illumination is necessary when:

- One or more approaches are illuminated.
- An illuminated area in the vicinity can distract the driver's view.
- Heavy nighttime traffic is anticipated.
Continuity of illumination must be provided between illuminated areas and the roundabout itself (5). An unlit roundabout with one or more illuminated approaches is dangerous. This is because a driver approaching on an unlit approach will be attracted to the illuminated area(s) and may not see the roundabout.

7.3.1.3 Rural conditions

For rural roundabouts, illumination is recommended but not mandatory. If there is no power supply in the vicinity of the intersection, the provision of illumination can be costly. When lighting is not provided, the intersection should be well signed and marked so that it can be correctly perceived by day and night. The use of reflective pavement markers and retroreflective signs (including chevrons supplementing the ONE-WAY signs) should be used when lighting cannot be installed in a cost-effective manner.

Where illumination can be provided, any raised channelization or curbing should be illuminated. In general, a gradual illumination transition zone of approximately 80 m (260 ft) should be provided beyond the final trajectory changes at each exit (5). This helps drivers adapt their vision from the illuminated environment of the roundabout back into the dark environment of the exiting roadway, which takes approximately 1 to 2 seconds. In addition, no short-distance dark areas should be allowed between two consecutive illuminated areas (5).

7.3.2 Standards and recommended practices

The following standards and recommended practices should be consulted in completing the lighting plan:

- AASHTO, An Information Guide for Roadway Lighting (6). This is the basic guide for highway lighting. It includes information on warranting conditions and design criteria.
- AASHTO, Standard Specifications for Structural Supports for Highway Signs, Luminaires and Traffic Signals (7). This specification contains the strength requirements of the poles and bracket arms for various wind loads, as well as the frangibility requirements. All luminaire supports, poles, and bracket arms must comply with these specifications.
- IES RP-8: The American National Standard Practice for Roadway Lighting (8). This Recommended Practice, published by the Illuminating Engineering Society, provides standards for average-maintained illuminance, luminance, and small target visibility, as well as uniformity of lighting. Recommended illumination levels for streets with various classifications and in various areas are given in Exhibit 7-23.
Exhibit 7-23. Recommended street illumination levels.

<table>
<thead>
<tr>
<th>Street Classification</th>
<th>Area Classification</th>
<th>Average Maintained Illuminance Values</th>
<th>Illuminance Uniformity Ratio (Average to Minimum)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Arterial</td>
<td>Commercial</td>
<td>17 lx (1.7 fc)</td>
<td>3 to 1</td>
</tr>
<tr>
<td></td>
<td>Intermediate</td>
<td>13 lx (1.3 fc)</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Residential</td>
<td>9 lx (0.9 fc)</td>
<td></td>
</tr>
<tr>
<td>Collector</td>
<td>Commercial</td>
<td>12 lx (1.2 fc)</td>
<td>4 to 1</td>
</tr>
<tr>
<td></td>
<td>Intermediate</td>
<td>9 lx (0.9 fc)</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Residential</td>
<td>6 lx (0.6 fc)</td>
<td></td>
</tr>
<tr>
<td>Local</td>
<td>Commercial</td>
<td>9 lx (0.9 fc)</td>
<td>6 to 1</td>
</tr>
<tr>
<td></td>
<td>Intermediate</td>
<td>7 lx (0.7 fc)</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Residential</td>
<td>4 lx (0.4 fc)</td>
<td></td>
</tr>
</tbody>
</table>

Definitions:

Commercial: A business area of a municipality where ordinarily there are many pedestrians during night hours. This definition applies to densely developed business areas outside, as well as within, the central part of a municipality. The area contains land use which attracts a relatively heavy volume of nighttime vehicular and/or pedestrian traffic on a frequent basis.

Intermediate: Those areas of a municipality often with moderately heavy nighttime pedestrian activity such as in blocks having libraries, community recreation centers, large apartment buildings, industrial buildings, or neighborhood retail stores.

Residential: A residential development, or a mixture of residential and small commercial establishments, with few pedestrians at night.

Note: Values in table assume typical asphalt roadway surface (pavement classification R2 or R3). Consult the IES document for other pavement surfaces.

Source: Illuminating Engineering Society RP-8 (8)

73.3 General recommendations

The primary goal of illumination is to ensure perception of the approach and mutual visibility among the various categories of users. To achieve this, the following features are recommended:

- The overall illumination of the roundabout should be approximately equal to the sum of the illumination levels of the intersecting roadways. If the approaching roadways have been designed to the illumination levels given in Exhibit 7-23, this may result in illumination levels at the roundabout ranging from 9 lx (0.8 fc) for roundabouts at the intersection of local streets in residential areas to 36 lx (3.4 fc) for roundabouts at the intersection of arterials in commercial areas. Local illumination standards should also be considered when establishing the illumination at the roundabout to ensure that the lighting is consistent.

- Good illumination should be provided on the approach nose of the splitter islands, at all conflict areas where traffic is entering the circulating stream, and at all places where the traffic streams separate to exit the roundabout.

- It is preferable to light the roundabout from the outside in towards the center. This improves the visibility of the central island and the visibility of circulating vehicles to vehicles approaching to the roundabout. Ground-level lighting within the central island that shines upwards towards objects in the central island can improve their visibility.
7.3.4 Clear zone requirements

As discussed in Chapter 5, the proportion of single-vehicle crashes at roundabouts is high compared to other intersection types. This is because roundabouts consist of a number of relatively small-radii horizontal curves for each traveled path through the roundabout. Drivers travel on these curves with quite high values of side friction, particularly at roundabouts in higher speed areas. Single-vehicle crashes, which predominantly involve out-of-control vehicles, increase with an increased amount of side friction.

Because of the relatively high number of out-of-control vehicles, it is desirable to have adequate amounts of clear zone where there are no roadside hazards on each side of the roadway. Lighting supports and other poles should not be placed within small splitter islands or on the right-hand perimeter just downstream of an exit point. Lighting poles should be avoided in central islands when the island diameter is less than 20 m (65 ft).

The reader should refer to the AASHTO Roadside Design Guide for a more detailed discussion of clear zone requirements (9).

7.4 Work Zone Traffic Control

During the construction of a roundabout it is essential that the intended travel path be clearly identified. This may be accomplished through pavement markings, signing, delineation, channelizing devices, and guidance from police and/or construction personnel, depending on the size and complexity of the roundabout. Care should be taken to minimize the channelizing devices so that the motorist, bicyclist, and pedestrian has a clear indication of the required travel path. Each installation should be evaluated separately, as a definitive guideline for the installation of roundabouts is beyond the scope of this guide. Refer to Part 6 of the MUTCD for requirements regarding work zone traffic control.

7.4.1 Pavement markings

The pavement markings used in work zones should be the same layout and dimension as those used for the final installation. Because of the confusion of a work area and the change in traffic patterns, additional pavement markings may be used to clearly show the intended direction of travel. In some cases when pavement markings cannot be placed, channelizing devices should be used to establish the travel path.

7.4.2 Signing

The signing in work zones should consist of all necessary signing for the efficient movement of traffic through the work area, preconstruction signing advising the public construction signing for a roundabout should follow the MUTCD standard.
lic of the planned construction, and any regulatory and warning signs necessary for the movement of traffic outside of the immediate work area. The permanent roundabout signing should be installed where practicable during the first construction stage so that it is available when the roundabout is operable. Permanent signing that cannot be installed initially should be placed on temporary supports in the proposed location until permanent installation can be completed.

7.4.3 Lighting

Permanent lighting, as described in Section 7.3, should be used to light the work area. If lighting will not be used, pavement markings, as described in Section 7.2, should be used.

7.4.4 Construction staging

As is the case with any construction project, before any work can begin, all traffic control devices should be installed as indicated in the traffic control plan or recommended typical details. This traffic control shall remain in place as long as it applies and then be removed when the message no longer applies to the condition.

Prior to work that would change the traffic patterns to that of a roundabout, certain peripheral items may be completed. This would include permanent signing (covered), lighting, and some pavement markings. These items, if installed prior to the construction of the central island and splitter islands, would expedite the opening of the roundabout and provide additional safety during construction.

When work has commenced on the installation of the roundabout, it is desirable that it be completed as soon as possible to minimize the time the public is faced with an unfinished layout or where the traffic priority may not be obvious. If possible, all work, including the installation of splitter islands and striping, should be done before the roundabout is open to traffic.

If it is necessary to leave a roundabout in an uncompleted state overnight, the splitter islands should be constructed before the central island. Any portion of the roundabout that is not completed should be marked, delineated, and signed in such a way as to clearly outline the intended travel path. Pavement markings that do not conform to the intended travel path should be removed.

It is highly desirable to detour traffic for construction of a roundabout. This will significantly reduce the construction time and cost and will increase the safety of the construction personnel. If it is not possible to detour all approaches, detour as many approaches as possible and stage the remainder of the construction as follows:

1. Install and cover proposed signing.
2. Construct outside widening if applicable.
3. Reconstruct approaches if applicable.
4. Construct splitter islands and delineate the central island. At this point the signs should be uncovered and the intersection should operate as a roundabout.

5. Finish construction of the central island.

### 7.4.5 Public education

It is important to educate the public whenever there is a change in traffic patterns. It is especially important for a roundabout because a roundabout will be new to most motorists. The techniques discussed in Chapter 2 can be applied during the construction period. The following are some specific suggestions to help alleviate initial driver confusion.

- Hold public meetings prior to construction;
- Prepare news releases/handouts detailing what the motorist can expect before, during, and after construction;
- Install variable message signs before and during construction;
- Use Travelers Advisory Radio immediately prior to and during construction to disseminate information on “How to drive,” etc.; and
- Install signing during and after construction that warns of changed traffic patterns.

### 7.5 Landscaping

This section provides an overview of the use of landscaping in the design of a roundabout.

#### 7.5.1 Advantages

Landscaping in the central island, in splitter islands (where appropriate), and along the approaches can benefit both public safety and community enhancement.

The landscaping of the roundabout and approaches should:

- Make the central island more conspicuous;
- Improve the aesthetics of the area while complementing surrounding streetscapes as much as possible;
- Minimize introducing hazards to the intersection, such as trees, poles, walls, guide rail, statues, or large rocks;
- Avoid obscuring the form of the roundabout or the signing to the driver;
- Maintain adequate sight distances, as discussed in Chapter 6;
- Clearly indicate to the driver that they cannot pass straight through the intersection;
- Discourage pedestrian traffic through the central island; and
- Help blind and visually impaired pedestrians locate sidewalks and crosswalks.
7.5.2 Central island landscaping

The central island landscaping can enhance the safety of the intersection by making the intersection a focal point and by lowering speeds. Plant material should be selected so that sight distance (discussed in Chapter 6) is maintained, including consideration of future maintenance requirements to ensure adequate sight distance for the life of the project. Large, fixed landscaping (trees, rocks, etc.) should be avoided in areas vulnerable to vehicle runoff. In northern areas, the salt tolerance of any plant material should be considered, as well as snow storage and removal practices. In addition, landscaping that requires watering may increase the likelihood of wet and potentially slippery pavement. Exhibit 7-24 shows the recommended placement of landscaping within the central island.

The slope of the central island should not exceed 6:1 per the requirements of the AASHTO Roadside Design Guide (9).

Avoid items in the central island that might tempt people to take a closer look.

Where truck aprons are used in conjunction with a streetscape project, the pavement should be consistent with other streetscape elements. However, the material used for the apron should be different than the material used for the sidewalks so that pedestrians are not encouraged to cross the circulatory roadway. Street furniture that may attract pedestrian traffic to the central island, such as benches or monuments with small text, must be avoided. If fountains or monuments are being considered for the central island, they must be designed in a way that will enable proper viewing from the perimeter of the roundabout. In addition, they must be located and designed to minimize the possibility of impact from an errant vehicle.

Exhibit 7-24. Landscaping of the central island.

7.5.3 Splitter island and approach landscaping

In general, unless the splitter islands are very large or long, they should not contain trees, planters, or light poles. Care must be taken with the landscaping to avoid obstructing sight distance, as the splitter islands are usually located within the critical sight triangles (see Chapter 6).
Landscaping on the approaches to the roundabout can enhance safety by making the intersection a focal point and by reducing the perception of a high-speed through traffic movement. Plant material in the splitter islands (where appropriate) and on the right and left side of the approaches can help to create a funneling effect and induce a decrease in speeds approaching the roundabout. Landscaping in the corner radii will help to channelize pedestrians to the crosswalk areas and discourage pedestrians from crossing to the central island.

7.5.4 Maintenance

A realistic maintenance program should be considered in the design of the landscape features of a roundabout. It may be unrealistic to expect a typical highway agency to maintain a complex planting plan. Formal agreements may be struck with local civic groups and garden clubs for maintenance where possible. Liability issues should be considered in writing these agreements. Where there is no interest in maintaining the proposed enhancements, the landscape design should consist of simple plant materials or hardscape items that require little or no maintenance.

7.6 References


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Chapter 8 System Considerations

Roundabouts have been considered as isolated intersections in most other international roundabout guides and publications. However, roundabouts may need to fit into a network of intersections, with the traffic control functions of a roundabout supporting the function of nearby intersections and vice versa. The purpose of this chapter is to provide some guidance on potentially difficult, but not uncommon, circumstances or constraints.

Many countries whose initial design and driver experience was with isolated roundabouts have since extended their application to transportation system design and operation. This chapter addresses the appropriate use of roundabouts in a roadway network context and the benefits obtained. Since the design of each roundabout should generally follow the principles of isolated roundabout design, the discussion is at a conceptual and operational level and generally complements the planning of isolated roundabouts discussed in Chapter 3. In many cases, site-specific issues will determine the appropriate roundabout design elements.

To establish some fundamental understanding for subsequent discussion, three design issues at an isolated roundabout are presented. First, this chapter will describe the requirements and effects of signal control of one or more legs of a roundabout, as well as the entire roundabout. It is noted that fully signalized roundabouts are not desirable. Next, modified designs that incorporate at-grade rail crossings are discussed. It is noted that intersections with rail lines passing through them or near them are not desirable. However, these situations do occur and would then need to be analyzed.

Building upon this understanding, the next sections address design and performance of two closely spaced roundabouts and the specific application to roundabout interchanges. This is followed by issues pertaining to the use of roundabouts on an arterial or network that may include or replace coordinated signalized intersections. Finally, the role of microscopic simulation models in assisting with analysis of these system effects is reviewed.

8.1 Traffic Signals at Roundabouts

Although yield control of entries is the default at roundabouts, when necessary, traffic circles and roundabouts have been signalized by metering one or more entries, or signalizing the circulatory roadway at each entry. Roundabouts should never be planned for metering or signalization. However, unexpected demand may dictate the need after installation. Each of these will be discussed in turn. In the first case, entrance metering can be implemented at the entrance or some distance upstream.
8.1.1 Metered entrance

Roundabouts operate effectively only when there are sufficient longer and acceptable gaps between vehicles in the circulatory lanes. If there is a heavy movement of circulating drivers, then entering drivers at the next downstream entry may not be able to enter. This situation occurs most commonly during the peak periods, and the performance of the roundabout can be greatly improved with entrance metering.

The concept of entrance metering at roundabouts is similar to ramp metering on freeways. A convenient sign is a changeable one that reads “Stop on red signal” and shows the usual yield sign for a roundabout otherwise. The sign would also include a yellow and red signal above the sign. The operation of the sign would be to show drivers the roundabout sign, display the yellow light and the sign “Stop on red signal,” and finally display the red light and the same text sign. This would cause entering vehicles to stop and allow the vehicles at the downstream entrance to proceed. A queue length detector on the downstream entrance may be used to indicate to the signal controller when the metering should be activated and deactivated. Once on the circulatory roadway, vehicles are not stopped from leaving the roundabout.

8.1.2 Nearby vehicular and pedestrian signals

Another method of metering is the use, with appropriate timing, of a nearby upstream signalized intersection or a signalized pedestrian crossing on the subject approach road. Unlike pure entry metering, such controls may stop vehicles from entering and leaving the roundabout, so expected queue lengths on the roundabout exits between the metering signal and the circulatory roadway should be compared with the proposed queuing space.

Because of additional objectives and constraints, metering by upstream signals is generally not as effective as direct entrance metering. However, a signalized pedestrian crossing may be desirable on its own merits. More than one entrance can be metered, and the analyst needs to identify operational states and evaluate each one separately to provide a weighted aggregate performance measure.

When disabled pedestrians and/or school children are present at a high-volume site, a pedestrian-actuated traffic signal could be placed 20 to 50 m (65 to 165 ft) from the yield line. This longer distance than at an unsignalized crossing may be required because the vehicle queues downstream of the roundabout exit will be longer. The trade-offs for any increased distance requirement are increased walking distances and higher exiting vehicle speeds. An analysis of signal timing will be needed to minimize queuing of vehicles into the roundabouts.
8.13 Full signalization of the circulatory roadway

Full signalization that includes control of circulating traffic at junctions with major entrances is possible at large-diameter multilane traffic circles or rotaries that have adequate storage space on the circulatory roadway. The double-lane roundabout dimensions resulting from the design criteria recommended in this guide may preclude such possibilities. As stated previously, full signalization should in any case only be considered as a retrofit alternative resulting from unanticipated traffic demands. Other feasible alternatives should also be considered, such as flaring critical approaches, along with the associated widening of the circulatory roadway; converting a large-diameter rotary to a more compact modern roundabout form; or converting to a conventional signalized intersection. This guide recommends that signalizing roundabouts to improve capacity be considered only when it is the most cost-effective solution.

Traffic signals at fully signalized rotaries should be timed carefully to prevent queuing on the circulatory roadway by ensuring adequate traffic progression of circulating traffic and especially critical movements. Introducing continuous or part-time signals on the circulatory roadway requires careful design of geometry, signs, lane markings, and signal timing settings, and literature on this specific topic should be consulted (1, 2).

8.2 At-Grade Rail Crossings

Locating any intersection near an at-grade railroad crossing is generally discouraged. However, roundabouts are sometimes used near railroad-highway at-grade crossings. Rail transit, including stations, have successfully been incorporated into the medians of approach roadways to a roundabout, with the tracks passing through the central island. In such situations, the roundabout either operates partially during train passage, or is completely closed to allow the guided vehicles or trains to pass through. The treatment of at-grade rail crossings should follow primarily the recommendations of the Manual on Uniform Traffic Control Devices (MUTCD) (3). Another relevant reference is the FHWA Railroad-Highway Grade Crossing Handbook (4).

There are essentially two ways in which rails can interact with a roundabout, as shown in Exhibit 8-1:

- Through the center; or
- Across one leg in close proximity to the roundabout.
In either case, traffic must not be forced to stop on the tracks. A new intersection should not be designed with railroad tracks passing through the center of it. However, on occasions, the rail line passes through an existing intersection area. The traffic engineer might be faced with a decision whether to change the intersection type to a roundabout or to grade-separate the crossing.

A gated rail crossing through the center of a roundabout can be accommodated in two ways. The first method is to prevent all vehicular traffic from entering the roundabout. The second method is to prevent traffic from crossing the tracks while still allowing some movements to occur. This latter method will have lower delays and queues, but it may be more confusing and less safe.

A gated rail crossing adjacent to a roundabout can be accommodated in two ways, as shown in Exhibit 8-2:

- **Method A: Closure only at rail crossing.** This method prohibits vehicles from crossing the rails but still allows vehicles to enter and leave the circulatory roadway. This method allows for many of the movements through the roundabout to continue to run free, if a queue does not build to the point of impeding circulation within the roundabout. A queuing analysis should be performed using the expected volume crossing the rails and the expected duration of rail crossing to determine the likelihood that this blockage will occur. In general, this method works better than Method B if there is sufficient separation between the roundabout and the rail crossing. If blockage is anticipated, the designer should choose Method B.

- **Method B: Closure at rail crossing and at most entries to the roundabout.** This method closes all entries to the roundabout except for the entry nearest the rail crossing. This allows any vehicles in the roundabout to clear prior to the arrival of the train. In addition, a gate needs to be provided on the approach to the rail crossing exiting the roundabout to protect against possible U-turns in the roundabout. This causes increased queuing on all approaches but is generally safer than Method A when there is insufficient storage capacity between the roundabout and rail crossing.

**Exhibit 8-1.** Rail crossing treatments at roundabouts.
8.3 Closely Spaced Roundabouts

It is sometimes desirable to consider the operation of two or more roundabouts in close proximity to each other. In these cases, the expected queue lengths at each roundabout become important. Exhibit 8-3 presents an example of closely spaced T-intersections. The designer should compute the 95th-percentile queues for each approach to check that sufficient queuing space is provided for vehicles between the roundabouts. If there is insufficient space, then drivers will occasionally queue into the upstream roundabout and may cause it to lock.

Exhibit 8-2. Methods for accommodating a rail crossing adjacent to a roundabout.
Closely spaced roundabouts may improve safety by “calming” the traffic on the major road. Drivers may be reluctant to accelerate to the expected speed on the arterial if they are also required to slow again for the next close roundabout. This may benefit nearby residents.

When roundabouts are used at offset T-intersections, there is an opportunity to bypass one through lane direction on the major road at each roundabout. Exhibit 8-4 presents sketches of through bypass lanes for the two basic types of offset T-intersection configurations. In both cases, through traffic in each direction needs to negotiate only one roundabout, and capacity is therefore typically improved. The weaving section should be analyzed both for capacity and for safety through an evaluation of the relative speeds of the weaving vehicles.
Of the two arrangements shown in Exhibit 8-4, Option A (roundabout precedes bypass) is preferred. The roundabout offers a visual cue to drivers to slow in Arrangement A and encourages slower (and therefore safer) driving through the two roundabouts. If Option B (bypass precedes roundabout) is used, the merges and diverges could occur at higher speeds. It may be appropriate in this case to omit the bypass lane and pass all through traffic through both roundabouts. Another advantage of Option A is that there would be less queuing of traffic on the road space between the roundabouts.

Note that when conventional T-intersections are used, Option A is less preferable than Option B due to the need to provide interior storage space for left turns in Option A. Therefore, roundabouts may be a satisfactory solution for cases like Option A.

**8.4 Roundabout Interchanges**

Freeway ramp junctions with arterial roads are potential candidates for roundabout intersection treatment. This is especially so if the subject interchange typically has a high proportion of left-turn flows from the off-ramps and to the on-ramps during certain peak periods, combined with limited queue storage space on the bridge crossing, off-ramps, or arterial approaches. In such circumstances, roundabouts operating within their capacity are particularly amenable to solving these problems when compared with other forms of intersection control.

**8.4.1 Two-bridge roundabout interchange**

There are two basic types of roundabout interchanges. The first is a large diameter roundabout centered over or under a freeway. The ramps connect directly into the roundabout, as do the legs from the crossroad. This is shown in Exhibit 8-5.

Exhibit 8-5. Two-bridge roundabout interchange.

The freeway may go either over or under the circulatory roadway.
This type of interchange requires two bridges. If the roundabout is above the freeway as shown in Exhibit 8-5, then the bridges may be curved. Alternatively, if the freeway goes over the roundabout then up to four bridges may be required. The number of bridges will depend on the optimum span of the type of structure compared with the inscribed diameter of the roundabout island and on whether the one bridge is used for both freeway directions or whether there is one bridge for each direction. The road cross-section will also influence the design decision. Exhibit 8-6 shows an example from the United Kingdom. The designer should decide if the expected speeds of vehicles at larger roundabouts are acceptable.

Exhibit 8-6. Examples of two-bridge roundabout interchanges.

A50/Heron Cross, United Kingdom  (mirrored to show right-hand-side driving)

8.4.2 One-bridge roundabout interchange

The second basic type uses a roundabout at each side of the freeway and is a specific application of closely spaced roundabouts discussed in the previous section. A bridge is used for the crossroad over the freeway or for a freeway to cross over the minor road. Again, two bridges may be used when the freeway crosses over the minor road.

This interchange form has been used successfully in some cases to defer the need to widen bridges. Unlike signalized ramps that may require exclusive left-turn lanes across the bridge and extra queue storage, this type of roundabout interchange exhibits very little queuing between the intersections since these movements are almost unopposed. Therefore, the approach lanes across the bridge can be minimized.

The actual roundabouts can have two different shapes or configurations. The first configuration is a conventional one with circular central islands. This type of configuration is recommended when it is desirable to allow U-turns at each roundabout or to provide access to legs other than the cross street and ramps. Examples from the United Kingdom and France are shown in Exhibit 8-7.
Exhibit 8-7. Examples of one-bridge roundabout interchanges with circular central islands.

Exhibit 8-7 (continued). Examples of one-bridge roundabout interchanges with circular central islands.

France
8.4.3 Analysis of roundabout interchanges

The traffic performance evaluation of the roundabout interchange is the same as for a single conventional roundabout. The maximum entry capacity is dependent on the circulatory flow and the geometry of the roundabouts. The evaluation process is included in Chapter 4.

The benefits and costs associated with this type of interchange also follow those for a single roundabout. A potential benefit of roundabout interchanges is that the queue length on the off-ramps may be less than at a signalized intersection. In almost all cases, if the roundabout would operate below capacity, the performance of the on-ramp is likely to be better than if the interchange is signalized. The headway between vehicles leaving the roundabout along the on-ramp is more random than when signalized intersections are used. This more random ramp traffic allows for smoother merging behavior on the freeway and a slightly higher performance at the freeway merge area compared with platooned ramp traffic from a signalized intersection.

Raindrop central islands make wrong-way movements more difficult, but require navigating two roundabouts to make a U-turn.

Exhibit 8-8. One-bridge roundabout interchange with raindrop-shaped central islands.

Interstate 70/Avon Road, Avon, CO

Roundabouts produce more random headways on ramps than signalized intersections, resulting in smoother merging behavior on the freeway.
The traffic at any entry is the same for both configurations. The entry capacity is the same and the circulating flow is the same for the large single roundabout (Exhibit 8-6) and for the second configuration of the two teardrop roundabout system (Exhibit 8-8). Note that the raindrop form may be considered and analyzed as a single large roundabout as in the circular roundabout interchange, but with a “pinched” waistline across or under one bridge rather than two. The relative performance of these systems will only be affected by the geometry of the roundabouts and islands. The system with the two circular roundabouts will have a slightly different performance depending upon the number of U-tums.

8.4.4 Geometric design parameters

The design parameters are not restrained by any requirement here. They are only constrained by the physical space available to the designer and the configuration selected. The raindrop form can be useful if grades are a design issue since they remove a potential cross-slope constraint on the missing circulatory road segments.

If there are more roads intersecting with the interchange than the single cross road, then two independent circular roundabouts are likely to be the best solution.

8.5 Roundabouts in an Arterial Network

In order to understand how roundabouts operate within a roadway system, it is important to understand their fundamental arrival and departure characteristics and how they may interact with other intersections. Exhibit 8-9 gives an example of a series of roundabouts along an arterial street.


The Avon Road network consists of five roundabouts (all pictured)—two at the interchange ramp terminals and three along the arterial south of the freeway.
8.5.1 Platooned arrivals on roundabout approaches

The performance of a roundabout is affected by its proximity to signalized intersections. If a signalized intersection is very close to the roundabout, it causes vehicles to enter the roundabout in closely spaced platoons; more importantly, it results in regular periods when no vehicles enter. These latter periods provide an excellent opportunity for traffic on the next downstream entry to enter. Since the critical gap is larger than the follow-up time, a roundabout becomes more efficient when the vehicles are handled as packets of vehicles rather than as isolated vehicles.

When the signalized intersection is some distance from the roundabout, then the vehicles’ arrival patterns have fewer closely spaced platoons. Platoons tend to disperse as they move down the road. The performance of a roundabout will be reduced under these circumstances when compared with a close upstream signal. If arrival speeds are moderate, then few longer gaps allow more drivers to enter a roundabout than a larger number of shorter gaps. If arrival speeds are low, then there are more opportunities for priority-sharing (where entering and circulating vehicles alternate) and priority-reversals (where the circulating vehicles tend to yield to entering vehicles) between entering and circulating traffic streams, and the influence of platoon dispersal is not as marked.

8.5.2 Roundabout departure pattern

Traffic leaving a roundabout tends to be more random than if another type of intersection control were used. A roundabout may therefore affect the performance of other unsignalized intersections or driveways more than if the intersection was signalized. However, as this traffic travels further along the road downstream of the roundabout, the faster vehicles catch up to the slower vehicles and the proportion of platooning increases.

In the case of a well-defined platoon from an upstream signalized intersection arriving at a downstream unsignalized intersection just after a well-defined platoon arrives from the other direction, it may be difficult for the minor street drivers at this unsignalized intersection to enter the link. If, on the other hand, one of these signalized intersections were to be replaced by a roundabout, then the effect of the random traffic from the roundabout might be relatively advantageous. Under these conditions, more dispersed platoons (or random) traffic could assist drivers entering along the link at the unsignalized intersection.

If a roundabout is used in a network of coordinated signalized intersections, then it may be difficult to maintain the closely packed platoons required. If a tightly packed platoon approached a roundabout, it could proceed through the roundabout as long as there was no circulating traffic or traffic upstream from the left. Only one circulating vehicle would result in the platoon breaking down. Hence, the use of roundabouts in a coordinated signalized network needs to be evaluated carefully. One possibility for operating roundabouts within a signal network is to signalize the major approaches of the roundabout and coordinate them with adjacent upstream and downstream signalized intersections.
Another circumstance in which a roundabout may be advantageous is as an alternative to signal control at a critical signalized intersection within a coordinated network. Such intersections are the bottlenecks and usually determine the required cycle length, or are placed at a signal system boundary to operate in isolated actuated mode to minimize their effect on the rest of the surrounding system. If a roundabout can be designed to operate within its capacity, it may allow a lowering of the system cycle length with resultant benefits to delays and queues at other intersections.

Because roundabouts accommodate U-turns more easily than do signals, they may also be useful as an access management tool. Left-turn exits from driveways onto an arterial which may currently experience long delays and require two-stage left-turn movements could be replaced with a simpler right turn, followed by a U-turn at the next roundabout.

### 8.5.3 Wide nodes and narrow roads

The ultimate manifestation of roundabouts in a system context is to use them in lieu of signalized intersections. Some European cities such as Nantes, France, and some Australian cities have implemented such a policy. It is generally recognized that intersections (or nodes), not road segments (or links), are typically the bottlenecks in urban roadway networks. A focus on maximizing intersection capacity rather than widening streets may therefore be appropriate. Efficient, signalized intersections, however, usually require that exclusive turn lanes be provided, with sufficient storage to avoid queue spillback into through lanes and adjacent intersections. In contrast, roundabouts may require more right-of-way at the nodes, but this may be offset by not requiring as many basic lanes on the approaches, relative to signalized arterials. This concept is demonstrated in Exhibit 8-10.

Analysis tools, such as those provided in Chapter 4, should be used to evaluate the arterial or network. These may be supplemented by appropriate use of microscopic simulation models as discussed next. Supplemental techniques to increase the capacity of critical approaches may be considered if necessary, such as bypass lanes, flaring of approaches and tapering of exits, and signalization of some roundabout approaches.
Exhibit 8-10. Wide nodes and narrow roads.
8.6 Microscopic Simulation

Microscopic simulation of traffic has become a valuable aid in assessing the system performance of traffic flows on networks, as recognized by the Highway Capacity Manual 2000 (7). Analysis of many of the treatments discussed in this chapter may benefit from the use of appropriate simulation models used in conjunction with analytic models of isolated roundabouts discussed in Chapter 4. These effects include more realistic modeling of arrival and departure profiles, time-varying traffic patterns, measurement of delay, spatial extent and interaction of queues, fuel consumption, emissions, and noise. However, the user must carefully select the appropriate models and calibrate the model for a particular use, either against field data, or other validated analytic models. It would also be advisable to check with others to see if there have been any problems associated with the use of the model.

8.6.1 How to use simulation

Microscopic simulation models are numerous and new ones are being developed, while existing models are upgraded frequently. Each model may have particular strengths and weaknesses. Therefore, when selecting a model, analysts should consider the following:

• Should a simulation model be used, or is an isolated analytic roundabout model sufficient?

• What are the model input requirements, are they sufficient, and how can they be provided or estimated?

• What outputs does the model provide in animated, graphical, or tabular form?

• What special features of the model are pertinent to the problem being addressed?

• Does the user manual for the simulation model specifically address modeling a roundabout?

• How sensitive is the model to various geometric parameters?

• Is there literature on the validation of this model for evaluating roundabouts?

• Is there sufficient information available on the microscopic processes being used by the model such as car following, gap acceptance, lane changing, or steering? (The availability of animation can assist in exposing model logic.)

• Are relevant past project examples available?

When a simulation model is used, the analyst is advised to use the results to make relative comparisons of the differences between results from changing conditions, and not to conclude that the absolute values found from the model are equivalent to field results. It is also advisable to perform a sensitivity analysis by changing selected parameters over a range and comparing the results. If a particular parameter is found
Simulation results are best used for relative comparisons, rather than relying on absolute values produced by the model. to affect the outcomes significantly, then more attention should be paid to accurate representation and calibration of this parameter. Finally, the analyst should check differences in results from using different random number seeds. If the differences are large, then the simulation time should be increased substantially.

8.6.2 Examples of simulation models

Five commercially available microscopic simulation models are CORSIM, Integration, Simtraffic, Paramics, and VISSIM. The first three are North American models; Paramics is from Scotland, and VISSIM is from Germany. The following sections present a brief overview of each model. Since software packages (and simulation models in particular) are in constant development, the user is encouraged to consult the most current information available on each model.

Exhibit 8-11. Summary of simulation models for roundabout analysis.

<table>
<thead>
<tr>
<th>Name</th>
<th>Scope</th>
<th>Notes (1999 versions)</th>
</tr>
</thead>
<tbody>
<tr>
<td>CORSIM</td>
<td>Urban streets, freeways</td>
<td>FHWA has been investigating modifications that may be required for CORSIM to adequately model controls such as stop and yield control at roundabouts through gap acceptance logic. In this research, roundabouts have been coded as a circle of four yield-controlled T-intersections. The effect of upstream signals on each approach and their relative offsets has also been reported (8).</td>
</tr>
<tr>
<td>Integration</td>
<td>Urban streets, freeways</td>
<td>Integration has documented gap acceptance logic for permitted movements at signal-, yield-, and stop-controlled intersections. As with CORSIM, Integration requires coding a roundabout simply as a series of short links and nodes with yield control on the entrances.</td>
</tr>
<tr>
<td>Simtraffic</td>
<td>Urban streets</td>
<td>Simtraffic is a simulation model closely tied to the signal timing software package Synchro. Simtraffic has the capability to model unsignalized intersections and thus may be suitable for modeling roundabouts. However, no publications to date have demonstrated the accuracy of Simtraffic in modeling roundabout operations.</td>
</tr>
<tr>
<td>Paramics</td>
<td>Urban streets, freeways</td>
<td>Paramics has been used in the United Kingdom and internationally for a wide range of simulation projects. It has been specifically compared with ARCADY in evaluating roundabouts (9). The model has a coding feature to automatically code a roundabout intersection at a generic node, which may then be edited. The model has been used in the United Kingdom for a number of actual roundabout evaluations. The model specifically employs a steering logic on the circulatory roadway to track a vehicle from an entry vector to a target exit vector (10).</td>
</tr>
<tr>
<td>VISSIM</td>
<td>Urban streets, transit networks</td>
<td>VISSIM is widely used in Germany for modeling urban road and transit networks, including roundabouts. Roundabout examples are provided with the software, including explicit modeling of transit and pedestrians. Modeling a roundabout requires detailed coding of link connectors, control, and gap acceptance parameters (11).</td>
</tr>
</tbody>
</table>
8.7 References


